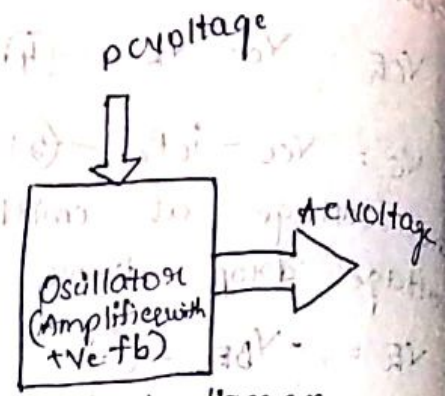


4 - Oscillators

Oscillator :-

An oscillator is an electronic ckt which produces AC of p voltage without any AC input, to produce an AC voltage it is energized with DC power supply.



Simple block diagram representation of oscillator.

It is an electronic ckt which converts DC voltage to AC voltage. Then it is also called DC to AC converter. An amplifier with +ve feedback is called an oscillator.

Principle of Oscillations :-

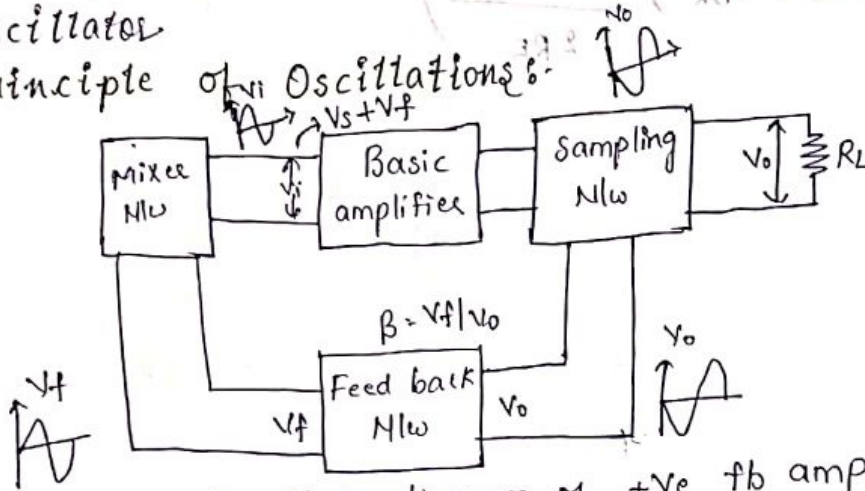


Fig: Block diagram of +ve fb amplifier.

The above figure shows an amplifier with +ve feedback. When DC power supply is switched on, noisy current is developed in the amplifier circuit and it is considered as the input of amplifier. Now the amplifier amplifies this noise input with 180° phase shift. The sampling Nlw is used to take the part of the output voltage and it is fed back to the input of amplifier through a feedback Nlw.

The feedback Nlw is so designed to provide another 180° phase shift. So that the total phase shift around the closed loop is 360°. Now the feedback signal is in phase with the input signal and it is added to the ip of amplifier.

$\therefore V_i = V_s + V_f$. It is further amplified by the basic amplifier. This process will be continued until sustained oscillations are generated.

Expression for gain with +ve fb:
The gain of an amplifier without fb is given by

$$A = \frac{V_o}{V_i} = \frac{V_o}{V_s} \quad \text{--- (1)}$$

By providing +ve fb, $V_i \rightarrow V_s + V_f$

$$A = \frac{V_o}{V_s + V_f}$$

$$AV_s + AV_f = V_o$$

$$AV_s + A\beta V_o = V_o$$

$$AV_s = V_o - A\beta V_o = V_o(1 - A\beta)$$

$$A_f = \frac{V_o}{V_s} = \frac{A}{1 - A\beta} \quad \text{--- (2)}$$

If the product of $A\beta = 1$

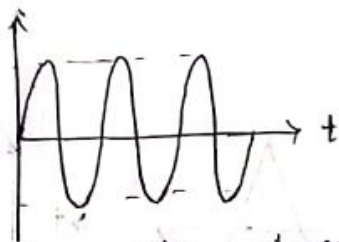
$$A_f = \frac{A}{1 - 1} = \infty$$

This indicates that the circuit produces an output without external input just by feeding its own input.

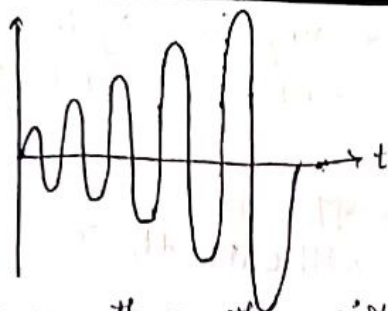
Barkhausen Criterion:

The Barkhausen criterion states that an amplifier with +ve feed back by satisfying the total phase shift around the closed loop is 360° and the product of A & $\beta = 1$, then the circuit works as an oscillator. In general, an amplifier with +ve feedback, the total phase shift around the closed loop is 360° .

1. If $A\beta = 1$, then the circuit generates sustained oscillations (or) undamped oscillations and it is shown in fig (a).

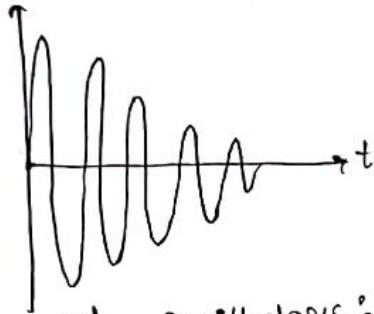


2) If $A\beta \neq 1$, then the circuit generates continuously increasing types of oscillations and it is shown in fig.



Over damped Oscillations

3) If $A\beta < 1$, then the circuit generates continuously decreasing type of oscillations (or) ^{dyt} undamped oscillations. It is as shown in fig.



Under damped oscillations

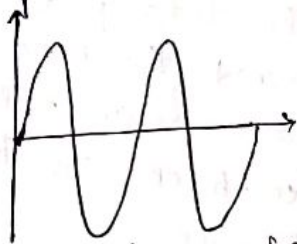
Classification of Oscillations:

Oscillations are classified based on four criteria.

I According to wave forms generated:

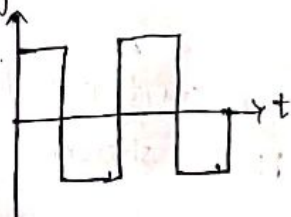
1. Sinusoidal Oscillations
2. Non Sinusoidal Oscillations.

→ The Sinusoidal Oscillations generates sinusoidal voltages (or) currents as shown in fig (a).

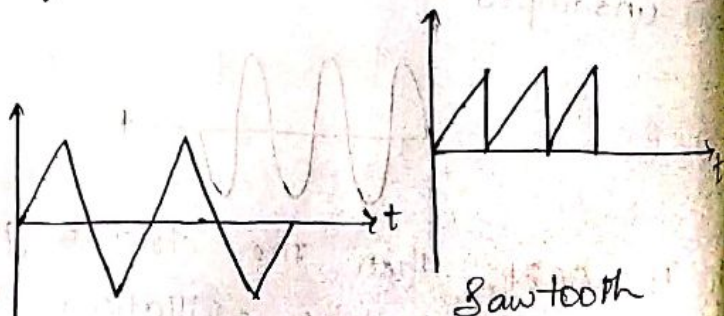


Sinusoidal waveform

→ Non sinusoidal Oscillations generates nonsinusoidal wave forms which are vary one or more times in a given cycle of time as shown in figures



Square waveform



triangular wave form

Sawtooth waveform

II. According to Fundamental Mechanisms used:

1. Negative Resistance Oscillators
2. Positive feedback Oscillators

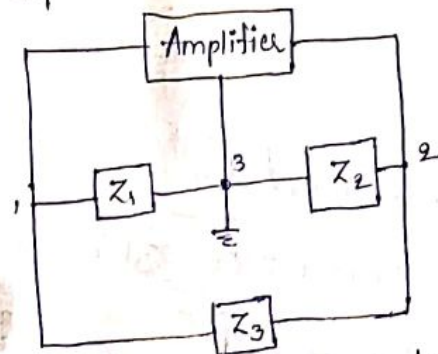
III. According to Frequency Range:

1. Audio frequency Oscillators - upto 20kHz
2. Radio frequency Oscillators - 20kHz - 30MHz
3. Very high frequency Oscillators : 30MHz - 300MHz
4. Ultra high frequency Oscillators : 300MHz - 3GHz
5. Microwave Oscillators : > 3GHz

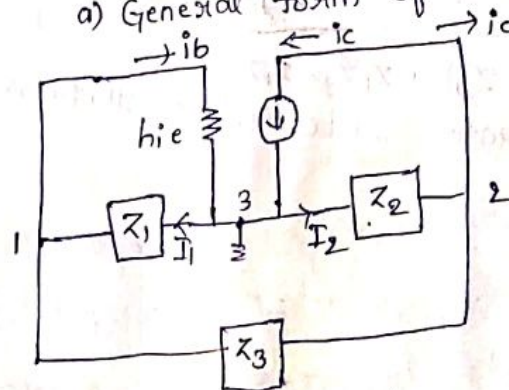
IV. According to Circuit Components: Sinusoidal Oscillators are further classified into 2 types.

1. LC Oscillators
 - a) Hartley Oscillator
 - b) Colpitts Oscillator
2. RC Oscillators
 - a) RC Phase shift Oscillator
 - b) Weinbridge Oscillator

General Expression for LC Oscillator:



a) General form of LC Oscillator



b) Equivalent ckt

fig(a) shows general form of LC oscillator. It consists of an amplifier with feedback N/w. As shown in fig(a), the feedback N/w is formed by 3 reactive elements Z_1, Z_2 & Z_3 . The reactive elements Z_1 & Z_2 acts as voltage divider N/w i.e., the voltage across Z_1 is feedback voltage & the voltage across Z_2 is o/p voltage. To determine condition to generate sustained oscillation, fig(a) is replaced by fig(b).

As shown in fig(b) h_{ie} & Z_1 are in parallel & their equivalent resistance is given by $Z' = \frac{Z_1 h_{ie}}{Z_1 + h_{ie}}$ (1)
The load impedance in b/w terminals 2 & 3 is the equivalent impedance of Z_2 in parallel with the series combination of Z' & Z_3 .

$$Z_L = Z_2 \parallel (Z' + Z_3)$$

$$Z_L = \frac{Z_2 (Z' + Z_3)}{Z_2 + Z' + Z_3} = \frac{Z_2 Z' + Z_2 Z_3}{Z_2 + \frac{Z_1 h_{ie}}{Z_1 + h_{ie}} + Z_3}$$

$$Z_L = \frac{Z_2 \left(\frac{Z_1 h_{ie}}{Z_1 + h_{ie}} \right) + Z_2 Z_3}{Z_2 + \left(\frac{Z_1 h_{ie}}{Z_1 + h_{ie}} \right) + Z_3}$$

$$= \frac{Z_1 Z_2 h_{ie} + Z_2 Z_3 Z_1 + Z_2 Z_3 h_{ie}}{Z_1 Z_2 + Z_2 h_{ie} + Z_1 h_{ie} + Z_1 Z_3 + Z_3 h_{ie}}$$

$$Z_L = \frac{Z_2 [Z_1 h_{ie} + Z_3 Z_1 + Z_3 h_{ie}]}{h_{ie} (Z_1 + Z_2 + Z_3) + Z_1 Z_2 + Z_1 Z_3} \quad \text{--- (2)}$$

The condition to generate sustained oscillations is

$$A\beta = 1 \quad \text{--- (3)}$$

$$\text{wkt } A = \frac{V_o}{V_i} \quad \text{--- (4)}$$

$$\text{where } V_o = I_L Z_L$$

$$= -\beta I_c Z_L$$

$$V_o = -h_{fe} \beta I_b Z_L \quad \text{--- (5)}$$

$$V_i = h_i e_i \beta \quad (6)$$

$$A = \frac{-h_f e_i \beta Z_L}{h_i e_i \beta}$$

$$A = \frac{-h_f e_i Z_L}{h_i e_i} \quad (7)$$

$$\beta = V_f / V_o \quad (8)$$

$$V_f = -I_1 Z' \quad (9)$$

The o/p voltage V_o in b/w terminals 2 & 3 in terms of current I_1 is given by

$$V_o = -I_1 (Z' + Z_3) \quad (10)$$

$$\beta = \frac{-I_1 Z'}{-I_1 (Z' + Z_3)}$$

$$\beta = \frac{Z_1 h_i e_i}{Z_1 + h_i e_i} = \frac{Z_1 h_i e_i}{Z_1 h_i e_i + Z_1 Z_3 + Z_3 h_i e_i}$$

$$\frac{Z_1 h_i e_i}{Z_1 + h_i e_i} + Z_3$$

$$\beta = \frac{Z_1 h_i e_i}{Z_1 Z_3 + h_i e_i (Z_1 + Z_3)} \quad (11)$$

Now A & β are sub. in eq (3)

$$\frac{-h_f e_i Z_L}{h_i e_i} \cdot \frac{Z_1 h_i e_i}{Z_1 Z_3 + h_i e_i (Z_1 + Z_3)} = 1$$

$$\frac{-h_f e_i Z_L Z_1}{Z_1 Z_3 + h_i e_i (Z_1 + Z_3)} = 1$$

$$-h_f e_i Z_1 \frac{Z_2 [Z_1 h_i e_i + Z_1 Z_3 + Z_3 h_i e_i]}{h_i e_i (Z_1 + Z_2 + Z_3) + Z_1 Z_2 + Z_1 Z_3} = 1$$

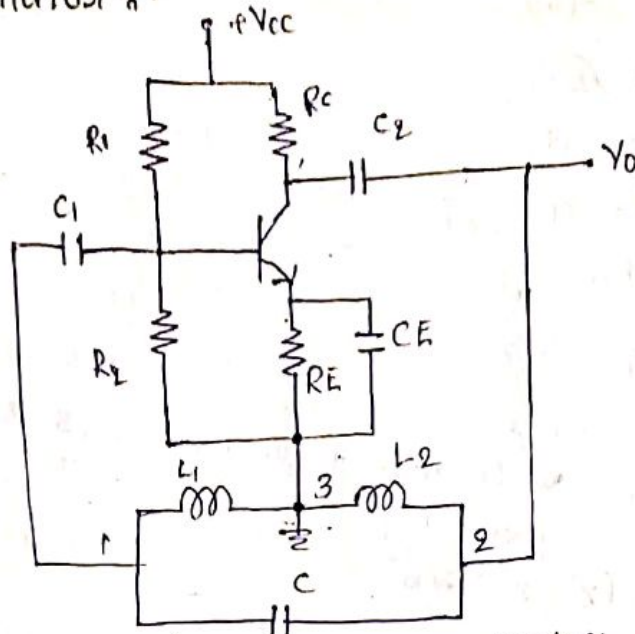
$$Z_1 Z_3 + h_i e_i (Z_1 + Z_3)$$

$$\Rightarrow -h_f e_i Z_1 Z_2 = h_i e_i (Z_1 + Z_2 + Z_3) + Z_1 Z_2 + Z_1 Z_3$$

$$\Rightarrow h_i e_i (Z_1 + Z_2 + Z_3) + Z_1 (Z_2 + Z_3) + h_f e_i Z_1 Z_2 = 0 \quad (12)$$

The above eq. is general expression of LC oscillator. By using this we can determine the frequency of LC oscillator.

Hartley Oscillator



ckt diagram of Hartley Oscillator

The above fig shows the circuit diagram of Hartley oscillator. It consists of an amplifier with feedback network. This feedback network is formed by two inductors and one capacitor i.e., the reactive elements Z_1 and Z_2 are inductors and Z_3 is capacitor.

Operation:
 when power supply $+V_{cc}$ is switched on, noisy currents developed within the amplifier circuit and it will be considered as input for same amplifier. Then amplifier amplifies noise inputs and this amplified noise output back to the feedback network.
 Due to this, oscillatory currents developed across L_1 & L_2 . The terminal 3 is grounded and it is at zero potential. If terminal 1 is at +ve potential with respect to terminal 3 at any instant and terminal 2 is at -ve potential with respect to terminal 3 at the same instant. Thus the phase shift b/w terminal 1 and terminal 2 is 180° and another 180° phase shift is provided by amplifier. The total phase shift around the closed loop is 360° . i.e., one of the condition is satisfied. and other condition $A\beta = 1$ is also satisfied by designing the feedback N/w. Then the ckt works as an Oscillator.

Frequency of Oscillation:
 wkt, the general expression of LC Oscillator is given by $h_{ie}(Z_1 + Z_2 + Z_3) + Z_1 Z_2(1 + h_{fe}) + Z_1 Z_3 = 0$ — (1)

The reactance of inductor L_1
 $Z_1 = j\omega L_1 + j\omega M = j\omega(L_1 + M)$ — (2)

The reactance of L_2
 $Z_2 = j\omega L_2 + j\omega M = j\omega(L_2 + M)$ — (3)

The reactance of C
 $Z_3 = \frac{1}{j\omega C}$ — (4)

Substitute eq (2), (3), (4) in (1).

$$h_{ie}(j\omega(L_1 + M) + j\omega(L_2 + M) + \frac{1}{j\omega C}) + j\omega(L_1 + M)(j\omega(L_2 + M))(1 + h_{fe}) + j\omega(L_1 + M) \frac{1}{j\omega C} = 0$$

$$h_{ie}j\omega(L_1 + L_2 + 2M + \frac{1}{j^2\omega^2 C}) + j^2\omega^2(L_1 + M)(L_2 + M)(1 + h_{fe}) + \frac{L_1 + M}{C} = 0$$

$$\Rightarrow h_{ie}j\omega(L_1 + L_2 + 2M - \frac{1}{\omega^2 C}) - \omega^2(L_1 + M)(L_2 + M)(1 + h_{fe}) + \frac{L_1 + M}{C} = 0$$

To determine the frequency of oscillation, the imaginary part of above eq. equate to zero.

$$h_{ie}j\omega(L_1 + L_2 + 2M - \frac{1}{\omega^2 C}) = 0$$

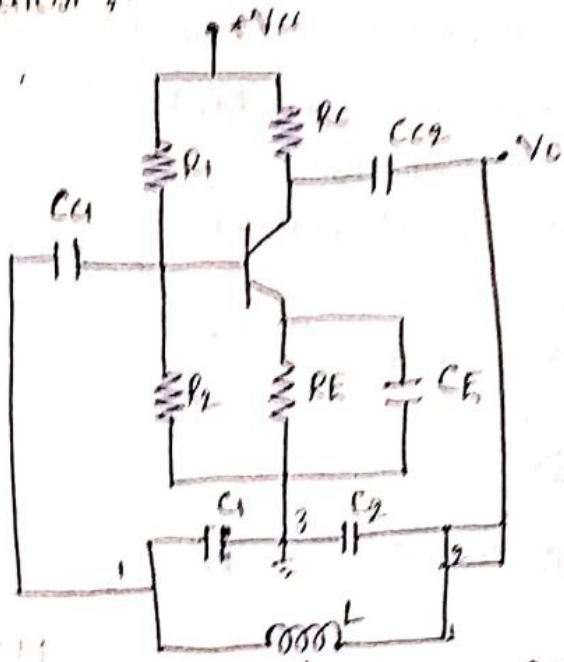
$$\Rightarrow L_1 + L_2 + 2M = \frac{1}{\omega^2 C}$$

$$\omega^2 = \frac{1}{(L_1 + L_2 + 2M)C}$$

$$\omega = \frac{1}{\sqrt{(L_1 + L_2 + 2M)C}}$$

$$f = \frac{1}{2\pi\sqrt{(L_1 + L_2 + 2M)C}} \quad \text{--- (5)}$$

Colpitts Oscillator



ckt diagram of colpitts Oscillator

→ Same theory as per Hartley Oscillator.

Frequency of oscillation:

The general expression of LC oscillator is given by

$$h_{ie}(Z_1 + Z_2 + Z_3) + Z_1 Z_2 (1 + h_{fe}) + Z_1 Z_3 = 0 \quad \text{--- (1)}$$

From the ckt diagram,

The reactance of capacitor C_1, C_2 is given by

$$Z_1 = \frac{1}{j\omega C_1} \quad \text{--- (2)}$$

$$Z_2 = \frac{1}{j\omega C_2} \quad \text{--- (3)}$$

$$Z_3 = j\omega L \quad \text{--- (4)}$$

Substitute eq 2, 3, 4 in eq (1)

$$h_{ie} \left[\frac{1}{j\omega C_1} + \frac{1}{j\omega C_2} + j\omega L \right] + \frac{1}{j\omega C_1} \cdot \frac{1}{j\omega C_2} (1 + h_{fe}) + \frac{1}{j\omega C_1} j\omega L = 0$$

$$\Rightarrow \frac{h_{ie}}{j\omega} \left[\frac{1}{C_1} + \frac{1}{C_2} + j\omega L \right] - \frac{1}{\omega^2 C_1 C_2} (1 + h_{fe}) + \frac{L}{C_1} = 0$$

$$\Rightarrow -h_{ie} j \frac{1}{\omega} \left[\frac{1}{C_1} + \frac{1}{C_2} - \omega^2 L \right] - \frac{1}{\omega^2 C_1 C_2} (1 + h_{fe}) + \frac{L}{C_1} = 0$$

To determine the frequency of oscillation, the imaginary part of above eq. is equating to zero.

$$\Rightarrow \frac{-hi e j}{\omega} \left[\frac{1}{C_1} + \frac{1}{C_2} - \omega^2 L \right] = 0$$

$$\frac{1}{C_1} + \frac{1}{C_2} = \omega^2 L$$

$$\omega = \frac{1}{L} \left[\frac{1}{C_1} + \frac{1}{C_2} \right]$$

$$\omega = \sqrt{\frac{1}{L} \left[\frac{1}{C_1} + \frac{1}{C_2} \right]}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{1}{L} \left(\frac{C_1 + C_2}{C_1 C_2} \right)}$$

$$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{C_1 + C_2}{L C_1 C_2}} = \frac{1}{2\pi \sqrt{L C_{eq}}} \quad \text{--- (5)}$$

1. In a Hartley Oscillator, if $L_1 = 0.2 \text{ mH}$, $L_2 = 0.3 \text{ mH}$ and $C = 0.003 \mu\text{F}$, calculate the freq. of its oscillation.
 Given, $L_1 = 0.2 \text{ mH}$, $L_2 = 0.3 \text{ mH}$, $C = 0.003 \mu\text{F}$
 WKT $(\because M=0)$

$$f = \frac{1}{2\pi \sqrt{(L_1 + L_2) C}}$$

$$f = \frac{1}{2\pi \sqrt{(0.2 + 0.3) \times 10^{-3} \times 0.003 \times 10^{-6}}}$$

$$= \frac{1}{2\pi (1.224 \times 10^{-6})}$$

$$f = 0.130 \text{ MHz. (or) } 130 \text{ kHz.}$$

2. In the Hartley Oscillator, $L_2 = 0.4 \text{ mH}$ & $C = 0.004 \mu\text{F}$, if the freq. of oscillation is 120 kHz . Find the value of L_1 . (Neglect M)

$$\text{WKT } f = \frac{1}{2\pi \sqrt{(L_1 + L_2) C}}$$

$$120 \times 10^3 = \frac{1}{2\pi \sqrt{(L_1 + 0.4 \times 10^{-3}) (0.004 \times 10^{-6})}}$$

$$240\pi \times 10^3 = \frac{1}{\sqrt{(L_1 + 0.4 \times 10^{-3}) (0.004 \times 10^{-6})}}$$

$$\Rightarrow 5.68 \times 10^{11} = \frac{1}{(L_1 + 0.4 \times 10^{-3}) (0.004 \times 10^{-6})}$$

$$\Rightarrow 2272 = \frac{1}{(L_1 + 0.118 \times 10^{-3})}$$

$$\Rightarrow 2272L_1 + 0.9088 = 1$$

$$2272L_1 = 0.0912$$

$$L_1 = 4.01 \times 10^{-5} \text{ H}$$

$$L_1 = 0.0401 \text{ mH}$$

3) In a transistorized Hartley oscillator, the inductance core is 2mH, 20mH. while the freq. is to be changed from 950 kHz to 2050 kHz. calculate the range over which the capacitor is to be varied.

Given, $L_1 = 2 \text{ mH}$, $L_2 = 20 \text{ mH}$

$$f_1 = 950 \text{ kHz}, \quad C_1 = ?$$

$$f_2 = 2050 \text{ kHz}; \quad C_2 = ?$$

$$\text{Sol} \quad f = \frac{1}{2\pi \sqrt{(L_1 + L_2)C}}$$

$$\Rightarrow \sqrt{(L_1 + L_2)C_1} = \frac{1}{2\pi f_1}$$

$$\sqrt{(2 \times 10^{-3} + 20 \times 10^{-6})} \cdot \sqrt{C_1} = \frac{1}{2\pi (950 \times 10^3)}$$

$$0.0449 \sqrt{C_1} = 1.67 \times 10^{-7}$$

$$\sqrt{C_1} = 3.719 \times 10^{-6}$$

$$C_1 = 13.83 \text{ pF}$$

$$\Rightarrow \sqrt{(L_1 + L_2)C_2} = \frac{1}{2\pi f_2} = \frac{1}{2\pi \times 2050 \times 10^3}$$

$$0.0449 \sqrt{C_2} = 7.76 \times 10^{-8}$$

$$\sqrt{C_2} = 1.728 \times 10^{-6}$$

$$C_2 = 2.98 \text{ pF}$$

The range of capacitance is from 2.98 pF to 13.83 pF

4) $L_1 = 38 \mu\text{H}$, $L_2 = 12 \mu\text{H}$, $C = 500 \text{PF}$. Find the freq. of oscillation and feedback factor β .

wkt $f = \frac{1}{2\pi\sqrt{(L_1+L_2)C}}$

$$= \frac{1}{2\pi\sqrt{(38+12) \times 10^{-6} \times 500 \times 10^{-12}}}$$

$$= \frac{1}{2\pi\sqrt{2.5 \times 10^{-14}}} = \frac{1}{2\pi \times 1.58 \times 10^{-7}} = 0.10 \times 10^7$$

$$= 1 \times 10^6$$

$f = 1 \text{ MHz}$

$\beta = \frac{L_1}{L_2} = \frac{38}{12} = 3.16$

5) A colpitts Oscillator is designed with $C_1 = 100 \text{PF}$, $C_2 = 7500 \text{PF}$. The inductance is variable, determine the range of inductance values, if the freq. of oscillator is to vary b/w 950 KHz, and 2050 KHz.

wkt $f = \frac{1}{2\pi\sqrt{L C_{eq}}}$

$C_{eq} = 98.6 \text{ PF}$

$f_1 = \frac{1}{2\pi\sqrt{L_1 C_{eq}}}$

$$950 \times 10^3 = \frac{1}{2\pi\sqrt{L_1 (9.82 \times 10^{-6})}}$$

$\Rightarrow 59.21 = \frac{1}{\sqrt{L_1}}$

$\sqrt{L_1} = 0.016$

$L_1 = 2.85 \times 10^{-4}$

$L_1 = 0.285 \text{ mH}$

$\Rightarrow 2050 \times 10^3 = \frac{1}{\sqrt{L_2} \cdot 6.23 \times 10^{-5}}$

$\Rightarrow \sqrt{L_2} = 7.82 \times 10^{-3}$

$L_2 = 61.3 \mu\text{H}$

The inductance value changes from 0.28 mH to 0.061 mH

$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$

$$= \frac{(100 \times 7500) \times 10^{-24}}{(100 + 7500) \times 10^{-12}}$$

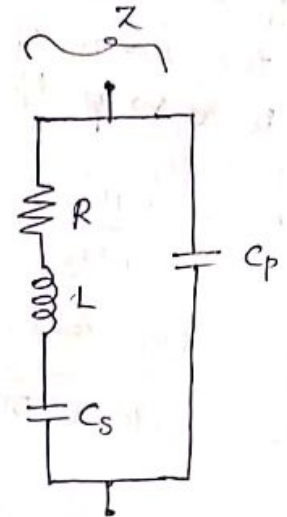
$127.90 = \frac{1}{\sqrt{L_2}}$

$\sqrt{L_2} = 7.81 \times 10^{-3}$

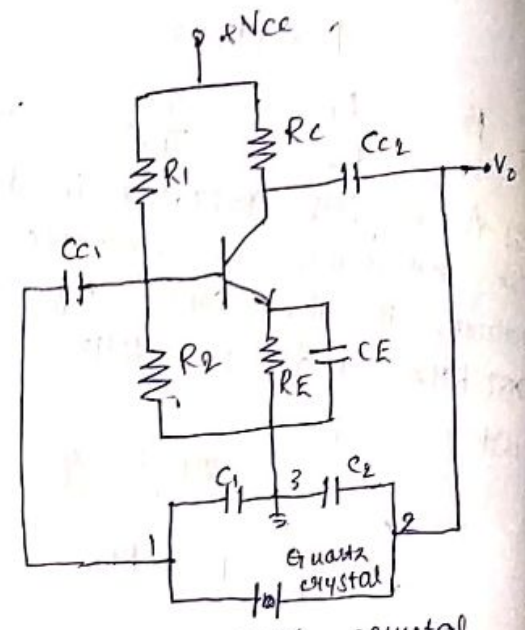
Why LC oscillators are not used at low frequencies.
 For LC oscillators, the frequency of oscillation is given by $f = \frac{1}{2\pi\sqrt{LC}}$. It clearly shows that the frequency of oscillation is inversely proportional to inductance and capacitance i.e., $f \propto \frac{1}{LC}$. If we design LC oscillators at low frequencies, it requires large values of inductors and capacitors which are having large space size and high cost.

This is the reason the LC oscillators are not used at low frequencies.

Crystal Oscillator:



b) Equivalent ckt of crystal



a) ckt diagram of crystal oscillator

Fig (a) shows the circuit diagram of crystal oscillator. It is similar to the colpitts oscillator except in feedback network inductor is replaced by quartz crystal. This oscillator works on the principle of piezo electric effect which states that when mechanical force is applied at one phase of crystal and it develops ac voltage at opposite phase of the crystal and in reverse when ac voltage is applied at one phase of the crystal and it develops mechanical vibrations at opposite phase of the crystal.

To determine the frequency of oscillation, quartz crystal is replaced by its equivalent circuit as shown in fig (b).

When crystal is not vibrating just it is represented by capacitor symbol (C_p) and when it is vibrating it is represented by series RLC circuit i.e. The internal losses are represented by resistor symbol, the magnetic field around the crystal is represented by inductor and the ac voltage which is developed by crystal is represented with the capacitor (C_s).

Frequency of oscillation:

As shown in fig (b), the equivalent impedance Z' is given by (neglecting internal losses)

$$Z = \left(j\omega h + \frac{1}{j\omega C_s} \right) \parallel \frac{1}{j\omega C_p}$$

$$= \frac{\left(j\omega h + \frac{1}{j\omega C_s} \right) \frac{1}{j\omega C_p}}{j\omega h + \frac{1}{j\omega C_s} + \frac{1}{j\omega C_p}}$$

$$= \frac{j\left(\omega h - \frac{1}{\omega C_s} \right) \frac{1}{j\omega C_p}}{j\left(\omega h - \frac{1}{\omega C_s} - \frac{1}{\omega C_p} \right)}$$

$$Z = \frac{\omega}{h} \frac{\left(\omega h - \frac{1}{\omega C_s} \right) \frac{1}{j\omega C_p}}{\left(\omega h - \frac{1}{\omega C_s} - \frac{1}{\omega C_p} \right)}$$

$$= \frac{\left(\omega^2 - \frac{1}{LC_s} \right) \frac{1}{j\omega C_p}}{\left[\omega^2 - \left(\frac{1}{LC_s} + \frac{1}{LC_p} \right) \frac{1}{h} \right]}$$

$$Z = \frac{\left(\omega^2 - \omega_s^2 \right) \frac{1}{j\omega C_p}}{\left[\omega^2 - \left(\frac{1}{LC_s} + \frac{1}{LC_p} \right) \frac{1}{h} \right]}$$

From the above equation, $\omega_s^2 = \frac{1}{LC_s}$

$$\Rightarrow \omega_s = \frac{1}{\sqrt{LC_s}}$$

$$f_s = \frac{1}{2\pi \sqrt{LC_s}}$$

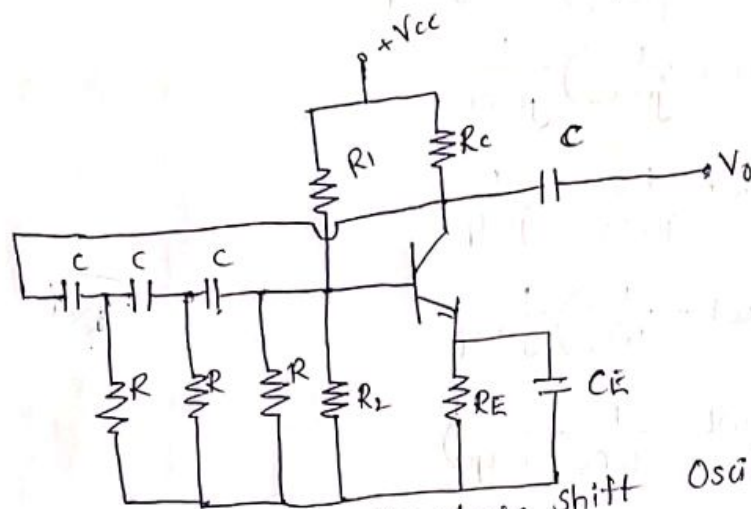
where $\omega_p^2 = \left(\frac{1}{C_s} + \frac{1}{C_p}\right) \cdot \frac{1}{L} = \frac{1}{LC_{eq}}$

$\omega_p = \sqrt{\left(\frac{1}{C_s} + \frac{1}{C_p}\right) \frac{1}{L}}$

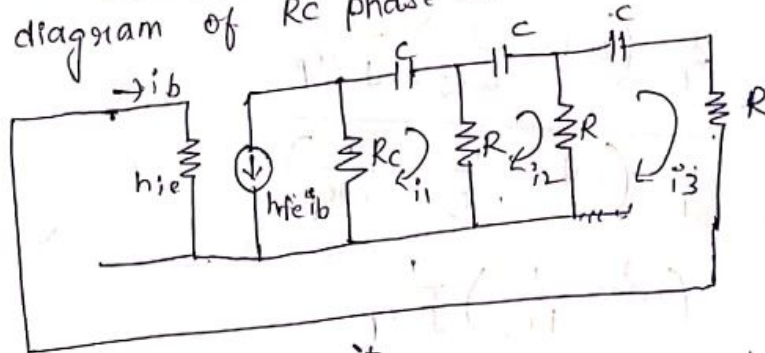
$\omega_p = \sqrt{\frac{C_p + C_s}{C_s C_p L}} = \frac{1}{\sqrt{LC_{eq}}}$

$f_p = \frac{1}{2\pi \sqrt{LC_{eq}}}$

RC - Phase shift Oscillator



a) ckt diagram of RC phase shift Oscillator.



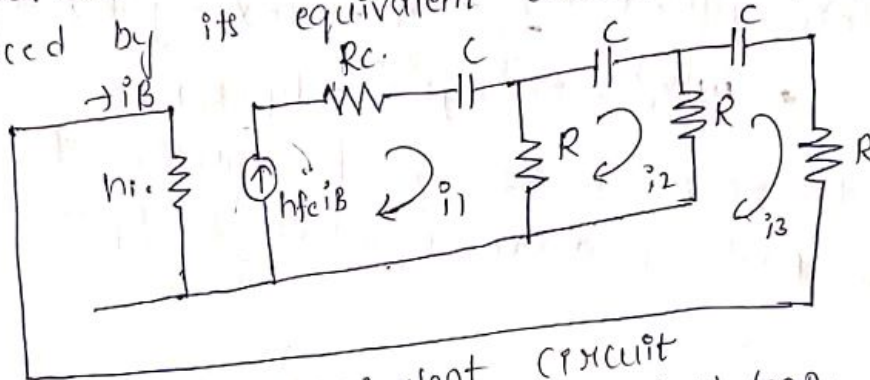
b) Equivalent circuit

Fig(a) shows the circuit diagram of RC phase shift oscillator. It consists of a CE amplifier and feedback network which is formed by 3 RC networks. when a power supply +Vcc is switched ON, noisy current is developed within the amplifier circuit and it will be considered as input for the amplifier circuit. Thus, an amplifier amplifies it with 180° phase shift and this amplified noise output back to the input of the amplifier through a feedback network.

In a feedback network, each RC network provides 60° phase shift. ∴, the phase shift provided by RC ladder network is 180°. Thus, the total phase shift around the closed loop is 360°. and by designing feedback network if $A\beta = 1$ then above circuit works as an oscillator.

Frequency of Oscillation:

To determine the frequency of oscillation, fig (a) is replaced by its equivalent circuit as shown in fig (b).



c) Simplified Equivalent Circuit

From fig (c), apply KVL to the first loop.

$$\Rightarrow hfe i_B R_c + i_1 R_e - i_1 j X_c + R(i_1 - i_2) = 0 \quad (i_B = i_3) \quad \text{--- (1)}$$

$$\Rightarrow i_1 (R_c - j X_c + R) + i_2 (-R) + i_3 hfe R_c = 0 \quad \text{--- (1)}$$

Apply KVL to the second loop.

$$\Rightarrow R(i_2 - i_1) - i_2 j X_c + R(i_2 - i_3) = 0$$

$$\Rightarrow -R i_1 + i_2 (R - j X_c + R) - R i_3 = 0 \quad \text{--- (2)}$$

Apply KVL to the third loop.

$$R(i_3 - i_2) - i_3 j X_c + R i_3 = 0$$

$$\Rightarrow -R i_2 + i_3 (R + R - j X_c) = 0 \quad \text{--- (3)}$$

From 1, 2, 3.

$$A = \begin{bmatrix} (R_c + R) - j X_c & -R & hfe R_c \\ -R & 2R - j X_c & -R \\ 0 & -R & 2R - j X_c \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix} = 0$$

$$\begin{vmatrix} R_c + R - j X_c & -R & hfe R_c \\ -R & 2R - j X_c & -R \\ 0 & -R & 2R - j X_c \end{vmatrix} = 0$$

$$\Rightarrow (R_c + R - jX_c) \left[(R - jX_c)^2 - R^2 \right] + R \left[-R(2R - jX_c) \right] + h_{fe} R_c R^2 = 0$$

$$\Rightarrow (R_c + R - jX_c) \left[4R^2 - j4RX_c - X_c^2 - R^2 \right] - 2R^3 + jR^2 X_c + h_{fe} R_c R^2 = 0$$

$$\Rightarrow (R_c + R - jX_c) (3R^2 - X_c^2 - j4RX_c) - 2R^3 + jR^2 X_c + h_{fe} R_c R^2 = 0$$

$$\Rightarrow 3R^2 R_c - R_c X_c^2 - j4RX_c R_c + 3R^3 - R X_c^2 - j4R^2 X_c - j3R^2 X_c + jX_c^3 + h_{fe} R_c R^2 = 0$$

$$\Rightarrow 4RX_c^2 - 2R^3 + jR^2 X_c + h_{fe} R_c R^2 = 0$$

$\Rightarrow R^3$ To determine frequency of oscillation, the imaginary part of above equation is equal to zero.

$$\Rightarrow -4RX_c R_c - 4R^2 X_c - 3R^2 X_c + X_c^3 + 2R^2 X_c = 0$$

$$\Rightarrow -6R^2 X_c + X_c^3 - 4RX_c R_c = 0$$

$$\Rightarrow X_c \left(X_c^2 - 6R^2 - 4RR_c \right) = 0$$

$$\Rightarrow X_c^2 = 6R^2 + 4RR_c$$

$$X_c^2 = \sqrt{R(6R + 4R_c)}$$

$$X_c = \sqrt{R^2 \left(6 + \frac{4R_c}{R} \right)}$$

$$\frac{1}{\omega C} = \sqrt{R^2 \left(6 + \frac{4R_c}{R} \right)}$$

$$\omega = \frac{1}{R_c \sqrt{6 + \frac{4R_c}{R}}}$$

$$f = \frac{1}{2\pi R_c \sqrt{6 + \frac{4R_c}{R}}}$$

$$\frac{R_c}{R} = k$$

$$f = \frac{1}{2\pi R_c \sqrt{6 + 4k}}$$

$$f = \frac{1}{2\pi \sqrt{LC}}$$

Wein bridge Oscillator :-

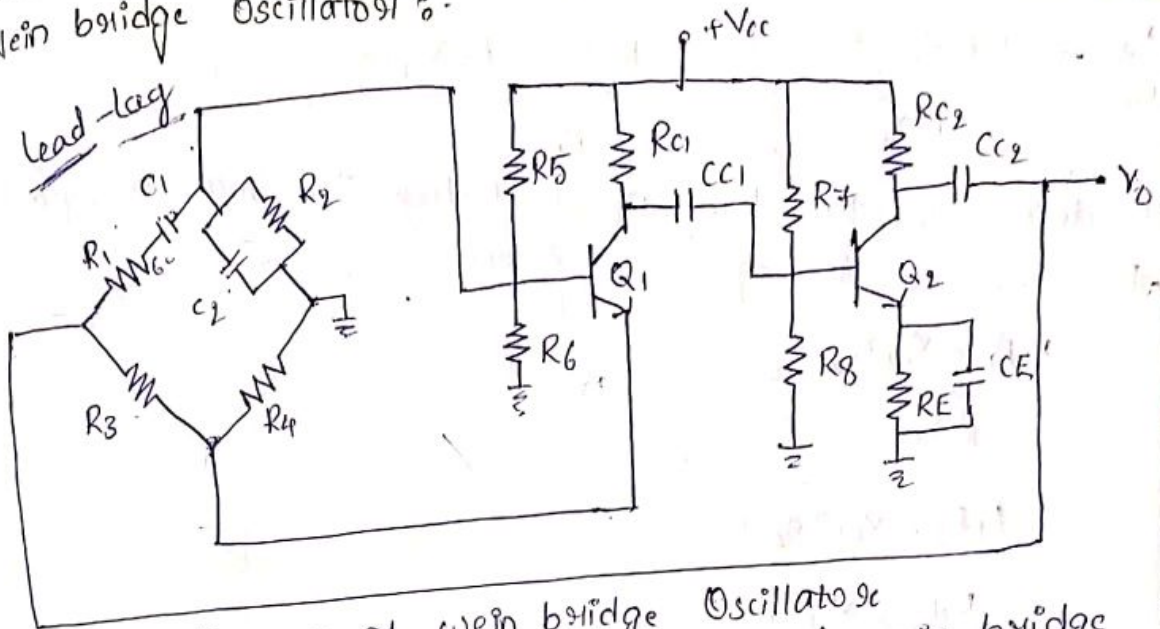


Fig: ckt diagram of wein bridge Oscillator
 The above fig. shows the ckt diagram of wein bridge Oscillator, it consists of two amplifier sections in CE mode and balanced bridge network each CE-amplifier stage provides 180° phase shift and the total phase shift by the two amplifier sections is 360° and hence no need to introduce any additional phase shift by the balanced bridge N/w. The lead-lag N/w which is formed by R1-C1 & R2-C2 provides the +ve feedback to the 1st stage of amplifier and the voltage divider N/w which is formed by R3 & R4 provides -ve fb to the emitter of 2nd stage of transistor. This balanced bridge N/w provides stability of oscillations in both amplitude & frequency.
 → To determine freq. of oscillation we consider the condition for balancing the bridge.

$$\begin{aligned}
 \text{i.e., } \frac{R_3}{R_4} &= \frac{R_1 + \frac{1}{j\omega C_1}}{R_2 \parallel \left(\frac{1}{j\omega C_2}\right)} \Rightarrow \frac{R_3}{R_4} = \frac{R_1 - jX_{C1}}{R_2 \parallel (-jX_{C2})} \\
 &= \frac{R_1 - jX_{C1}}{R_2(-jX_{C2})} = \frac{(R_1 - jX_{C1})(R_2 - jX_{C2})}{-jR_2X_{C2}} \\
 &= \frac{R_1R_2 - jR_1X_{C2} - jR_2X_{C1} - X_{C1}X_{C2}}{-jR_2X_{C2}} \\
 &= \frac{R_1R_2 - X_{C1}X_{C2}}{-jR_2X_{C2}} \cdot \frac{j(R_1X_{C2} + R_2X_{C1})}{jR_2X_{C2}}
 \end{aligned}$$

$$\frac{R_3}{R_4} \Rightarrow \frac{j(R_1 R_2 - X_{C1} X_{C2})}{R_2 X_{C2}} + \frac{R_1 X_{C2} + R_2 X_{C1}}{R_2 X_{C2}}$$

To determine the freq. of oscillation, the imaginary part of above eq. is equal to zero.

$$\frac{R_1 R_2 - X_{C1} X_{C2}}{R_2 X_{C2}} = 0$$

$$\Rightarrow R_1 R_2 - X_{C1} X_{C2} = 0$$

$$R_1 R_2 = X_{C1} X_{C2}$$

$$R_1 R_2 = \frac{1}{\omega C_1} \cdot \frac{1}{\omega C_2}$$

$$\omega^2 = \frac{1}{R_1 R_2 C_1 C_2}$$

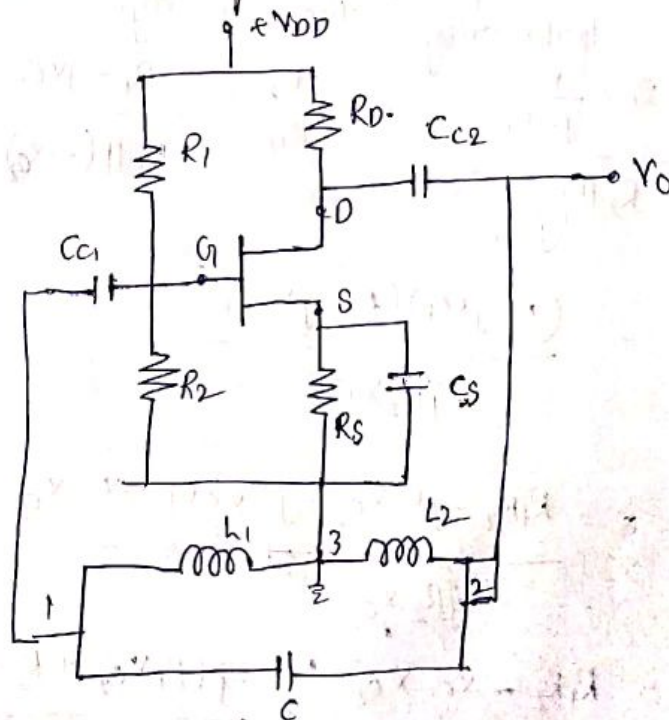
$$\omega = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}$$

$$f = \frac{1}{2\pi \sqrt{R_1 R_2 C_1 C_2}}$$

if $R_1 = R_2 = R$ & $C_1 = C_2 = C$

$$f = \frac{1}{2\pi RC}$$

Hartley oscillator using JFET :-



$$G.E - h_{ie} (z_1 + z_2 + z_3) + (1 + h_{fe}) z_1 z_2 + z_1 z_3 = 0$$

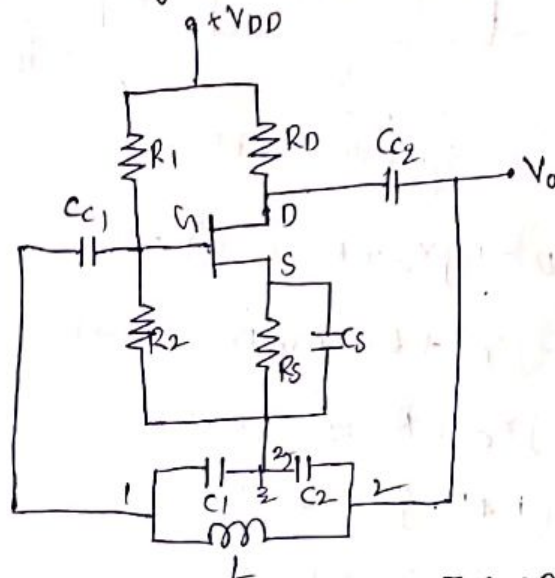
$$\rightarrow z_1 = j\omega R_1 + j\omega M = j\omega(L_1 + M)$$

$$z_2 = j\omega L_2 + j\omega M = j\omega(L_2 + M)$$

$$z_3 = \frac{1}{j\omega C}$$

$$f = \frac{1}{2\pi \sqrt{(L_1 + L_2 + 2M)C}}$$

Colpitts Oscillator using JFET:



$$G.E - h_{ie} (z_1 + z_2 + z_3) + (1 + h_{fe}) z_1 z_2 + z_1 z_3 = 0$$

$$z_1 = \frac{1}{j\omega C_1} \quad \text{--- (A)}$$

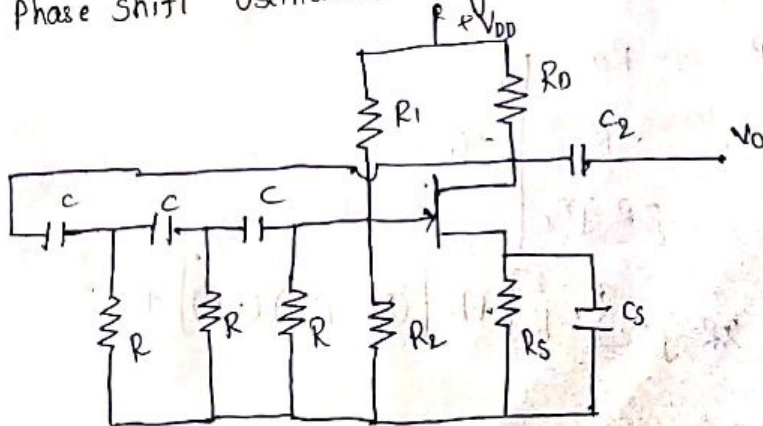
$$z_2 = \frac{1}{j\omega C_2}$$

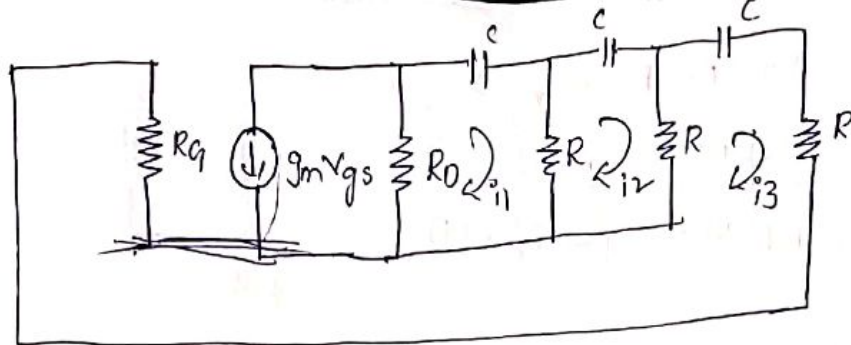
$$z_3 = j\omega L$$

$$f = \frac{1}{2\pi \sqrt{L C_{eq}}}$$

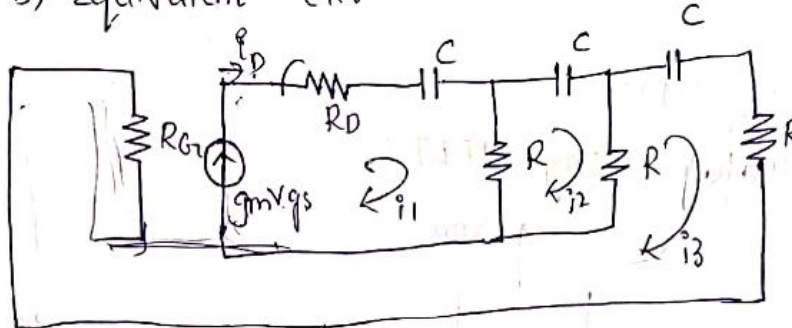
$$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$$

RC Phase shift Oscillator using JFET:





b) Equivalent ckt



c) Simplified Equivalent ckt

$$g_m = \frac{i_D}{V_{gs}}$$

$$\rightarrow gmV_{gs}R_D + i_1R_D - i_1jX_C + R(i_1 - i_2) = 0$$

$$\Rightarrow i_1(R_D + R - jX_C) + Ri_2 + i_3R_D = 0 \quad \text{--- (1)}$$

$$\rightarrow R(i_2 - i_1) - i_2jX_C + R(i_2 - i_3) = 0$$

$$\Rightarrow -i_1R + i_2(2R - jX_C) - Ri_3 = 0$$

$$-Ri_1 + i_2(2R - jX_C) - Ri_3 = 0 \quad \text{--- (2)}$$

$$\rightarrow R(i_3 - i_2) - jX_C i_3 + Ri_3 = 0$$

$$\Rightarrow -Ri_2 + i_3(2R - jX_C) = 0 \quad \text{--- (3)}$$

$$\begin{bmatrix} R_D + R - jX_C & -R & R_D \\ -R & 2R - jX_C & -R \\ 0 & -R & 2R - jX_C \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{vmatrix} R_D + R - jX_C & -R & R_D \\ -R & 2R - jX_C & -R \\ 0 & -R & 2R - jX_C \end{vmatrix} = 0$$

$$\Rightarrow (R_D + R - jX_C) \left[(2R - jX_C)^2 - R^2 \right] + R \left[(2R - jX_C)(-R) \right] + R_D \left[R^2 \right] = 0$$

$$\Rightarrow (R_D + R - jX_C) [4R^2 - 4RjX_C - X_C^2] R + R[-2R^2 + jX_C R] + R_D R^2 = 0$$

$$\Rightarrow (R_D + R - jX_C) (3R^2 - 4RjX_C - X_C^2) + 2R^3 + jX_C R^2 + R_D R^2 = 0$$

$$\Rightarrow 3R^2 R_D - 4R_D R jX_C - R_D X_C^2 + 3R^3 - 4R^2 jX_C + R X_C^2 - 3R jX_C + 2R^3 + jX_C R^2 + R_D R^2 = 0$$

To determine the frequency of oscillation, the imaginary part of above eq. is zero.

$$jX_C^3 + jX_C R^2 - 3R^2 jX_C - 4R^2 jX_C - 4R_D R jX_C = 0$$

$$X_C^2 + R^2 - 3R^2 - 4R^2 - 4R_D R = 0$$

$$X_C^2 - 6R^2 - 4R_D R = 0$$

$$X_C^2 = 6R^2 + 4R_D R$$

$$X_C^2 = R(6R + 4R_D)$$

$$X_C = \sqrt{R^2 \left(6 + \frac{4R_D}{R}\right)}$$

$$\frac{1}{\omega C} = \sqrt{R^2 \left(6 + \frac{4R_D}{R}\right)}$$

$$\omega = \frac{1}{RC \sqrt{6 + \frac{4R_D}{R}}}$$

$$f = \frac{1}{2\pi RC \sqrt{6 + \frac{4R_D}{R}}}$$

$$K = \frac{R_D}{R}$$

$$f = \frac{1}{2\pi RC \sqrt{6 + 4K}}$$

Frequency and amplitude stability of oscillator? In the Weinbridge oscillator, if the RC NWS consists of resistors of $200k\Omega$ and the capacitors of $300pF$, find its frequency of oscillation.

$$f = \frac{1}{2\pi \sqrt{R_1 C_1 R_2 C_2}}$$

$$R_1 = R_2 = 200k\Omega, \quad C_1 = C_2 = 300pF$$

$$f = \frac{1}{2\pi RC} = \frac{1}{2\pi \times 200 \times 10^3 \times 300 \times 10^{-12}}$$

$$= \frac{10^5}{12\pi}$$

$$f = 2.652 \text{ kHz}$$

Frequency and amplitude stability of oscillator :-

Frequency stability of an oscillator :-
 The frequency stability of an oscillator is a measure of its ability to maintain the required frequency over a long time interval. The main drawback in transistor oscillator is that the frequency of operation is not stable during a long time operation. The following are the factors which contribute to the change in frequency.

- i) Due to change in temperature the value of the frequency determining components such as resistor, inductor and capacitor changes.
- ii) Due to variations in the power supply, change in climatic conditions and due to aging of components the transistor parameters changes.
- iii) The effective resistance of the tank ckt is changed when the load is connected.
- iv) Due to variations in biasing conditions and loading conditions.

In the absence of automatic temp. control, the effect of temp. on the LC ckt can be reduced by selecting the inductance 'L' with +ve temperature coefficient and capacitance 'C' with -ve temperature coefficient.

As Piezo-electric crystals have high 'Q' values of the order of 10^5 , they can be used as parallel resonant circuits in oscillators to get very high frequency stability.

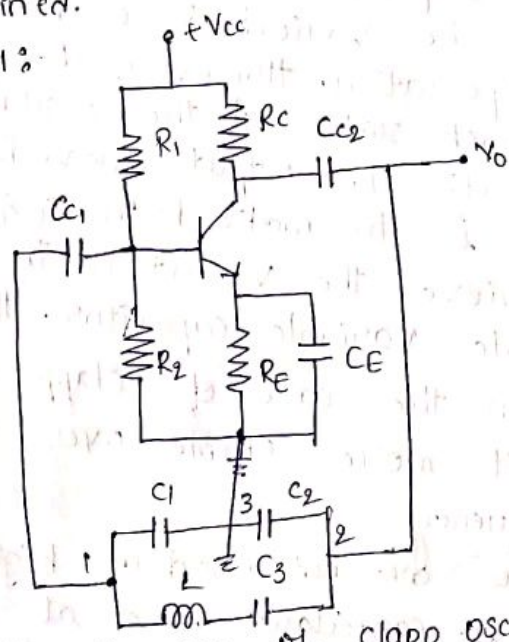
Amplitude stability of an Oscillator?

All oscillators not require +ve feed back for their operation. If the +ve resistance of the LC tank ckt is cancelled by introducing the right amount of -ve resistance across the tank ckt, then the steady oscillation can be maintained.

There are several devices such as Thermistor, UJT and tunnel diode exhibits a region of -ve resistance in V-I characteristics. Such devices operated in negative resistance region are placed across LC ckt as the frequency determining section.

In the case of RC oscillators, the amplitude against the variations due to aging of the transistors and other components can be stabilized by replacing the resistor in bridge by sensistors, which are temperature dependent resistors. Thus, the stability in amplitude of the RC oscillators can be easily maintained.

Clapp Oscillator?



a) ckt diagram of clapp oscillator
 - Clapp oscillator is an advanced version of colpitts oscillator in which an additional capacitor C_3 is added into the tank circuit to be in series with the inductor as shown in figure.
 Apart from the presence of extra capacitor, all other components and their connections remain similar to that in the case of colpitts oscillator.

Hence, the working of this circuit is almost similar to that of the Colpitts oscillator. However, the frequency of oscillation in the case of Clapp oscillator is given by

$$f = \frac{1}{2\pi \sqrt{L \left(\frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} \right)}}$$

Usually, the value of C_3 is chosen that to be much smaller than the other two capacitors. This is because at higher frequencies, smaller the C_3 , larger will be the inductor, which simplifies the implementation as well as reduces the effect of leakage inductance.

However, it is to be noted that when C_3 is chosen to be smallest with comparison in C_1 & C_2 , the net capacitance will be more dependent on it. Thus,

$$f = \frac{1}{2\pi \sqrt{L C_3}}$$

In the case of Colpitts oscillator, the capacitor C_1 (or) C_2 need to be varied in order to vary its frequency of operation. However, during this process even the feedback ratio of the oscillator changes which in turn affects its output waveform. One solution to this problem is to make both C_1 & C_2 to be fixed, while achieve the variation in frequency using a separate variable capacitor. This is what the C_3 does in the case of Clapp oscillator, which in turn makes it more stable over Colpitts in terms of frequency.

Why RC oscillators are not used at high frequency?
 The 'C' in RC is capacitance and at high frequencies the capacitor reactance will decrease than at low frequencies. As capacitor performance goes down, the circuit performance also goes down. Thus, RC oscillators performance is poor at high frequencies and not provides stable oscillations. This is the reason RC oscillators are not used at high frequencies.