

After striking the drain, characteristics of an n-channel enhancement type MOSFET, we can say that V_{GS} increases beyond threshold value, the density of free carriers (electrons) in the induced channel increases, increasing the drain current.

However at some point of V_{DS} , for constant V_{GS} , the drain current reaches a saturation level.

The value of V_{DS} at this point is known as pinch-off voltage (V_p). The smaller off of I_D is due to a pinch-off process.

The characteristics of transfer is quite different from that obtained for JFET and depletion type MOSFET. We know that I_D does not flow until $V_{GS} = V_T$

for $V_{GS} > V_T$ the relationship b/w drain current and V_{GS} is non linear & given

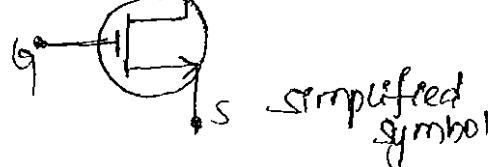
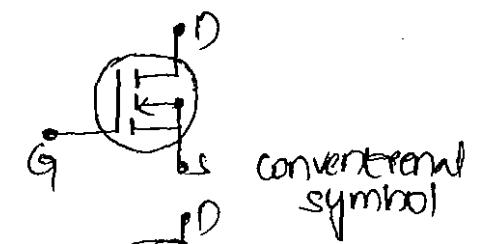
$$I_D = k(V_{GS} - V_T)^2 \quad \text{where } k = \frac{I_D(\text{ON})}{(V_{GS(\text{ON})} - V_T)^2}$$

$k \rightarrow$ conduction parameter, general $k = \frac{WnCox}{2L} (V_{GS(\text{ON})} - V_T)^2$

$Cox \rightarrow$ oxide capacitance per unit area; $Cox = \frac{\epsilon_{ox}}{t_{ox}}$

$t_{ox} \rightarrow$ oxide thickness; ϵ_{ox} is the oxide permittivity.

$W \rightarrow$ channel width, $L \rightarrow$ channel length.



n-channel Enhancement
type MOSFET



p-channel Enhancement
type MOSFET

Transistor biasing and thermal stabilization

Region of operation	Emitter Base junction	Collector Base junction
Cutoff	Reverse biased	Reverse biased.
Active	Forward biased	Reverse biased
Saturation	Forward biased	Forward biased.

In order to operate transistor in the desired region we have to apply external d.c. voltages of correct polarity and magnitude to the two junctions of the transistor. This is nothing but biasing of the transistor. Because d.c. voltages are used are used to bias the transistor, biasing is known as d.c. biasing of the transistor.

Need for Biasing:

In transistor amplifier circuit, output signal power is always greater than input signal power. Now the question is how this amplification of power is achieved. The d.c. sources (d.c. biasing) supplies the power to the transistor circuit to get the output signal power greater than input signal power. thus we can say that the biasing is needed.

To operate the transistor in the desired region

to get one op signal power greater than input signal power.

Q point and Stability factor:

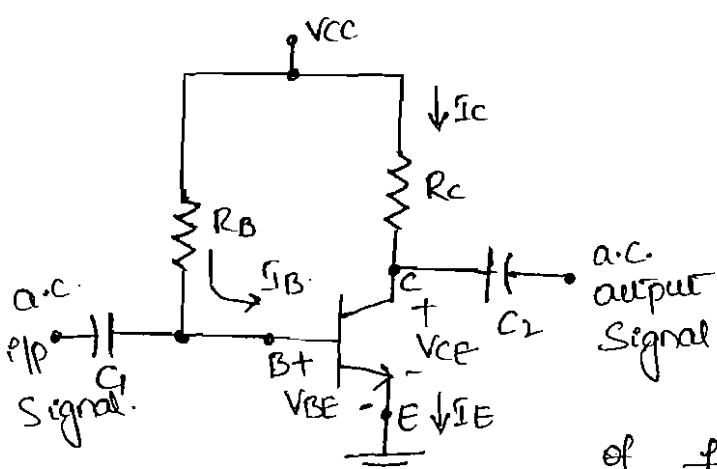
When we bias a transistor we establish a certain current and voltage conditions for the transistor. These conditions are known as operating conditions (or) d.c. operating point (or) quiescent point.

The operating point must be stable for proper operation of the transistor. However the operating point changes in transistor

Temperature dependent factors are V_T , β , I_{CBO} etc.

- Temperature dependent, the operating point also varies with change in temperature. The stability factor indicates the deg of change in operating point due to variation in β , I_{CBO} etc.

Fixed Bias Circuit:



The fig shows the fixed bias circuit. It is the simplest d.c. bias configuration. For the d.c. analysis we can replace capacitor with an open circuit because the reactance of the capacitor for d.c. is $X_C = \frac{1}{2\pi f C} = 0$. The d.c. equivalent of fixed bias circuit is shown below.

Base Circuit:

Applying Kirchhoff's voltage law to the base circuit

$$\text{we get, } V_{CC} - I_B R_B - V_{BE} = 0 \quad \text{so} \quad I_B = \frac{V_{CC} - V_{BE}}{R_B} \rightarrow ①$$

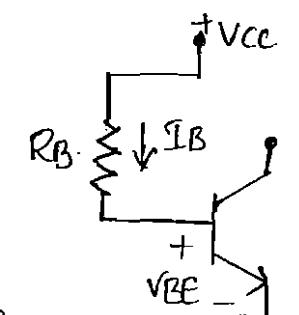
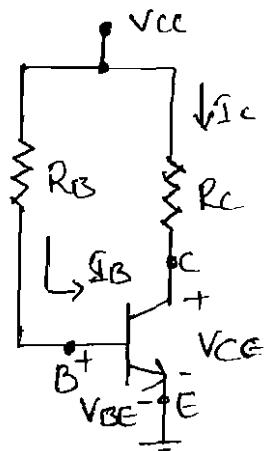
Consider the collector circuit, applying Kirchhoff's law at the collector we get $V_{CC} - I_C R_C - V_{CE} = 0$

$$\Rightarrow V_{CE} = V_{CC} - I_C R_C \rightarrow ②$$

The magnitude of collector current is given by

$$I_C = \beta I_B \quad \& \quad I_C = \frac{V_{CC} - V_{CE}}{R_C}$$

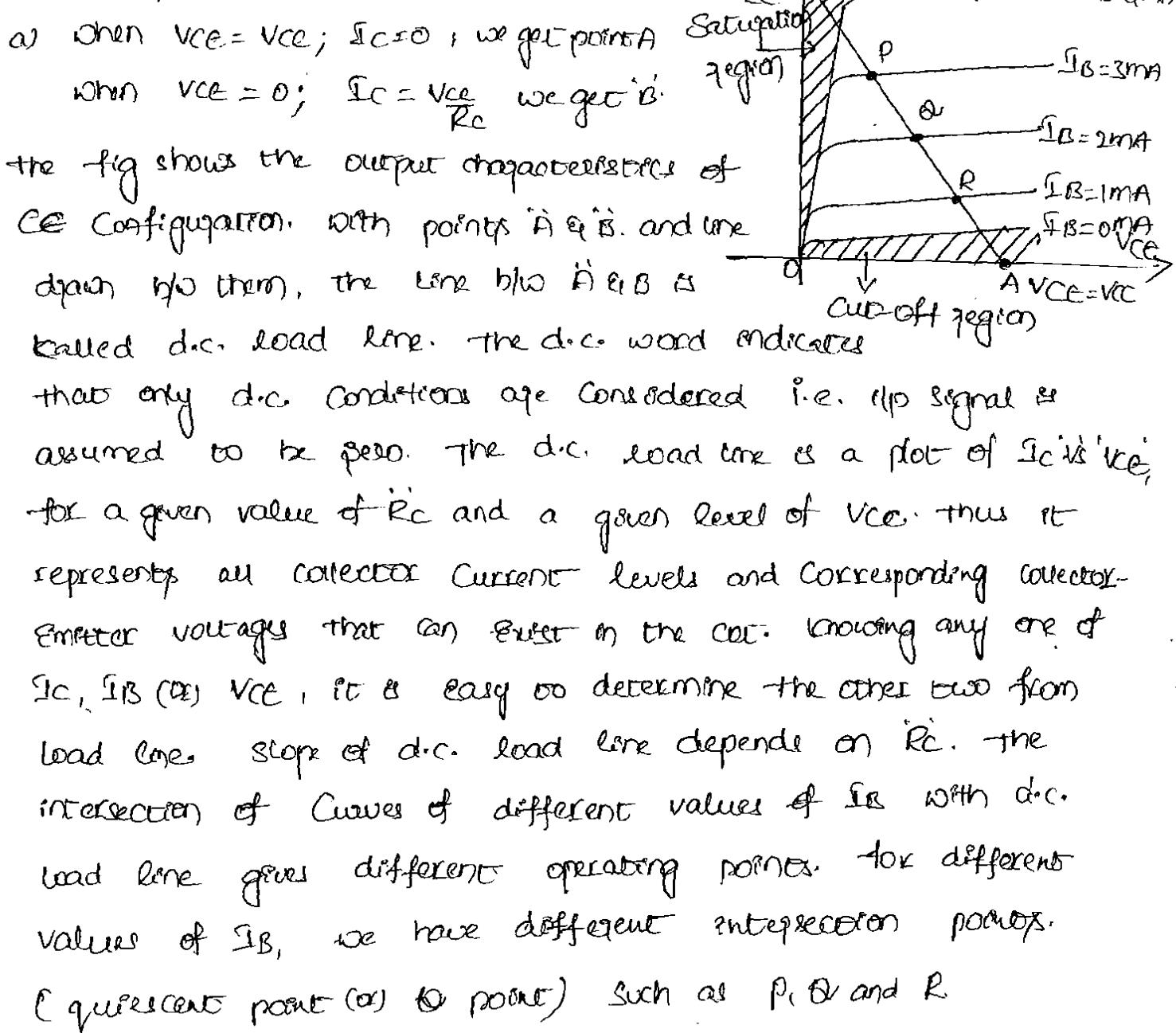
It is important to note that since the base current is controlled by the value of R_B and I_C is related to I_B by a constant β , the magnitude of I_C is not a function of R_C . changing R_C to any level will not effect the level of $\beta(I_B)I_C$ as long as we remain in active region of the device. However the change in R_C will change the value of V_{CE} .



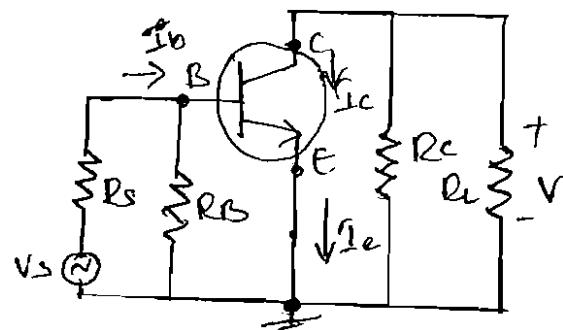
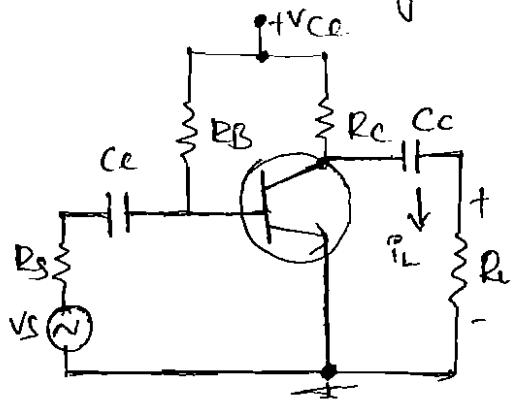
Load line and Quiescent point

D.C. load line: for fixed bias circuit we have $I_C = \frac{V_{CC} - V_{CE}}{R_C}$

$I_C = \frac{V_{CC}}{R_C} - \frac{1}{R_C} V_{CE} = (-\frac{1}{R_C}) V_{CE} + \frac{V_{CC}}{R_C}$ By comparing this eqn. with equation of straight line $y = mx + c$, m is slope of line, and c is y -intercept on y -axis. we can draw a line on the graph of I_C versus V_{CE} which is having slope of $-\frac{1}{R_C}$ and y -intercept of $\frac{V_{CC}}{R_C}$



Coupling capacitors and by-pass capacitor acts as a short circuit.
Remember that capacitor blocks d.c. signal and passes a.c. signal.
we replace d.c. source by a short circuit, i.e. V_{CC} and ground lines.



The resulted a.c. equivalent circuit for the given CE amplifier is shown, from it, the collector cat resistance seen by the d.c. bias current I_{DC} is $R_{DC} = R_L$. However it is apparent that collector signal current I_c sees a collector circuit resistance $R_{AC} = R_C \parallel R_L = \frac{R_C R_L}{R_C + R_L}$; since $R_{DC} \neq R_{AC}$, in general the concept of a.c. load line arises.

Applying KVL to the collector circuit of the a.c. equivalent circuit
 $V_{ce} = I_c R_{AC}$ where. $V_{ce} =$ a.c. collector to emitter voltage
 $I_c =$ a.c. collector current.

Since $I_c = i_c - I_{CO}$ and $V_{ce} = V_{CEO} - V_{CE}$

where i_c : total instantaneous collector current

V_{CE} : total instantaneous collector to emitter voltage.

$$\text{so } V_{ce} = V_{CEO} - V_{CE} = (i_c - I_{CO}) R_{AC} \Rightarrow$$

$$i_c = \frac{V_{CEO}}{R_{AC}} - \frac{V_{CE}}{R_{AC}} + I_{CO}.$$

All excursions of the a.c. signals i_c , and V_{ce} are represented by points on a.c. load line. If $i_c = I_{CO}$ is substituted in above we find that $V_{CE} = V_{CEO}$. This indicates that a.c. load line is a straight line at that point.

Let's find the points at which the collector areas will intercept the areas of the d.c characteristics of CE configuration.

point a: by setting $I_C = 0$

$$V_{CEmax} = V_{CEO} + I_C \cdot R_{AC} \rightarrow \textcircled{A}$$

point b: by setting $V_{CE} = 0$

$$I_{Cmax} = \frac{V_{CEO}}{R_{AC}} + I_{CO} \rightarrow \textcircled{B}$$

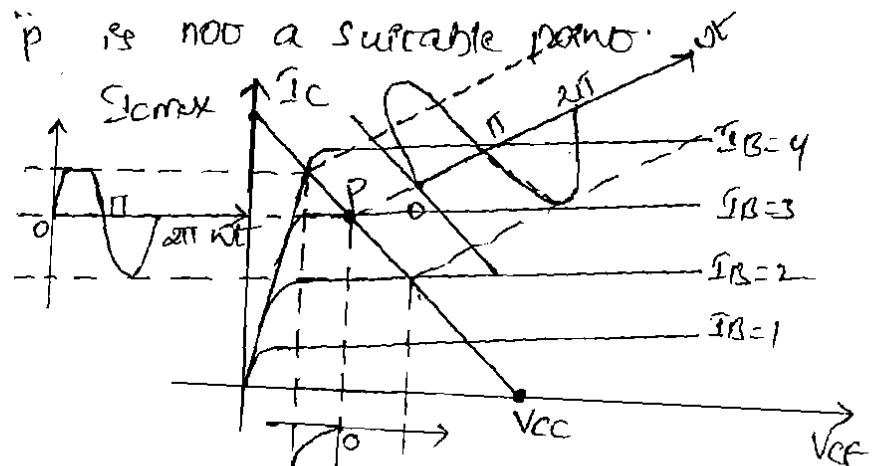
Selection of operating point:

The operating point can be selected at different positions on d.c. load line, near saturation region, near cut-off region, (a) at the center, i.e. in active region. The selection of operating point will depends on its application. When transistor is used as an amplifier, the Q point should be selected at the center of the d.c. load line to prevent any possible distortion in the amplified output signal.

Case 1: Biasing Circuit is designed to fix a point at p.

Let point p is very nearer to saturation region. The collector current is clipped at the +ve cycle. So even though base current varies sinusoidally, collector current is not a useful sinusoidal waveform. i.e. distortion is present at the o/p. So point p is not a suitable point.

Operating point near saturation point gives clipping at +ve peaks



case 2: Biasing is in cut-off region.

a Q point at R, point K is very far from the collector-emitter line. The collector current is clipped at -ve half cycle, so point R is also not suitable for operating point.

case 3: Biasing circuit is designed to fix a Q point at point Q. The QP is sinusoidal waveform without any distortion. This point Q is the best operating point.

Typical junction voltages & conditions for operating region

Below table shows the typical junction voltages for Cut-off, active and saturation regions for n-p-n silicon and germanium transistors.

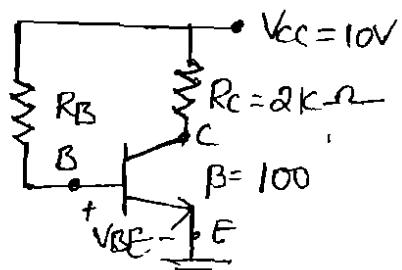
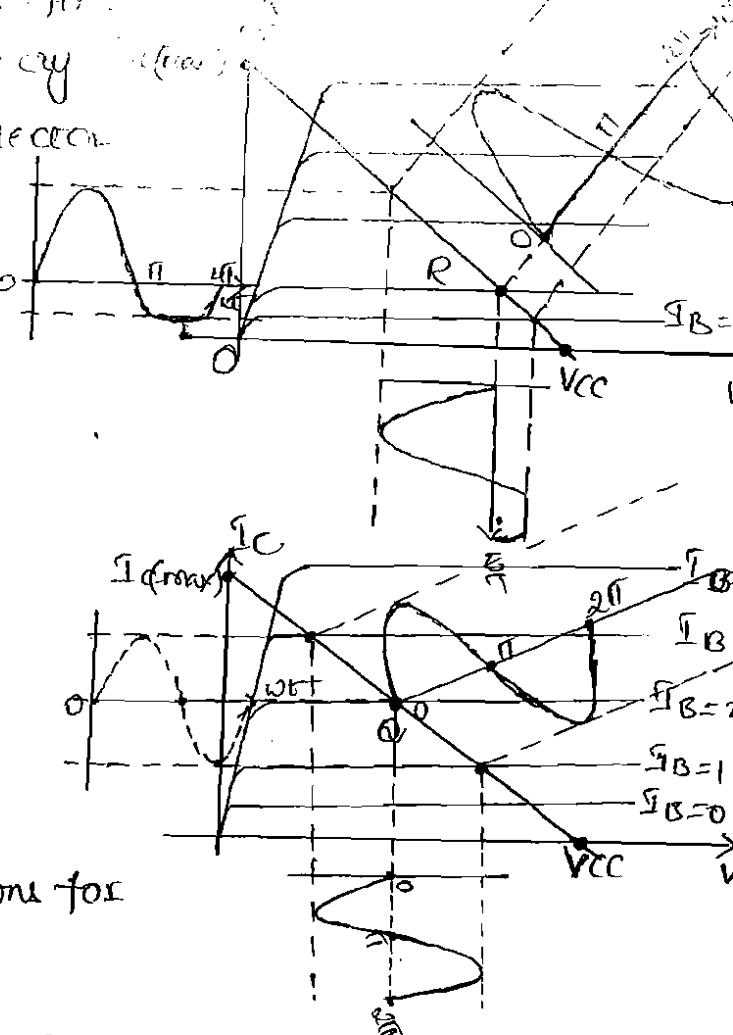
Transistor	$V_{CE(sat)}$	$V_{BE(sat)}$	$V_{BE(\text{active})}$	$V_{BE(\text{cut-off})}$	$V_{BE(\text{cut-off})}$
Si	0.2	0.8	0.7	0.5	0V
Ge	0.1	0.3	0.2	0.1	-0.1V

To identify the operating region of transistor, we can observe certain conditions. They are

$$\text{for saturation } I_B > \frac{I_C}{B_{ds}}$$

$$\text{for active region: } V_{CE} > V_{CE(sat)}$$

In the shows circuit, for $R_B = 300\text{k}\Omega$, & $R_E = 150\text{k}\Omega$, calculate I_B , I_C and V_{CE} and determine region of operation.



Given $I_C = 10 \text{ mA}$

Since Base-Emitter junction is not reverse biased, we can say that transistor is not Cut-off region, let assume transistor is operating in active region.

Applying KVL around base loop we get

$$V_{CC} = I_B R_B + V_{BE} \quad \text{Let } V_{BE} = 0.7 \text{ V}$$

$$V_{CC} = I_B \times 300 \times 10^3 + 0.7 = 10 \text{ V}$$

$$\Rightarrow I_B = \frac{9.3}{300 \times 10^3} = 31 \mu\text{A}$$

$$\text{In active region } I_C = \beta I_B = 100 \times 31 \times 10^{-6} \text{ A} = 3.1 \text{ mA}$$

Now by applying KVL around collector loop we get

$$V_{CC} = I_C R_C + V_{CE}$$

$$10 = 3.1 \times 10^{-3} \times 2 \times 10^3 + V_{CE}$$

$$V_{CE} = 10 - 6.2 = 3.8 \text{ V}$$

$V_{CE} > V_{CE(\text{sat})}$, collector to base junction is reverse biased and we can say that our assumption that transistor is in active region is justified.

Calc 2: $R_B = 150 \text{ k}\Omega$

Since Base-Emitter junction is not reverse biased hence transistor is not in Cut-off region, and assume it is in active region, hence KVL around base is

$$V_{CC} = I_B R_B + V_{BE} \Rightarrow I_B = \frac{10 - 0.7}{150 \times 10^3} = 62 \mu\text{A}$$

$$\text{In active region } I_C = \beta I_B \Rightarrow I_C = 6.2 \text{ mA}$$

KVL around collector

$$V_{CC} = I_C R_C + V_{CE} \Rightarrow V_{CE} = 10 - 6.2 \times 10^{-3} \times 2 \times 10^3 = 10 - 12.4 = -2.4 \text{ V}$$

It is important to note that collector voltage has to be zero (or) positive hence our assumption of transistor in active region is wrong. so it is in saturation

$$V_{CE} = (V_B + V_{BE}) - \frac{I_C}{R_C} \cdot R_C = V_{CE} - I_C R_C$$

Applying KVL around collector loop we get

$$V_{CE} = I_C R_C + V_{CE}(\text{sat}) \Rightarrow I_C = \frac{10 - 0.2}{2 \times 10^3} = 4.9 \text{ mA}$$

To justify transistor in saturation $I_B > \frac{I_C}{\beta}$

$$\Rightarrow \frac{I_C}{\beta} = \frac{4.9 \text{ mA}}{100} = 49 \mu \text{A} \text{ so } (I_B = 61.33 \mu \text{A}) (49 \mu \text{A} = \frac{I_C}{\beta}) \text{ hence}$$

our assumption that transistor is in saturation is justified.

Stabilization against variations in I_{CO} , V_{BE} and β .

As we know that biasing circuit should be designed to fix the operating point (or) Q point at the center of active region.

But only fixing of operating point is not sufficient. While designing biasing circuit, care should be taken so that the operating point will not shift into an undesirable region. (i.e. Cut off (or) saturation region) Designing one bias circuit to stabilize the Q point is known as bias stability.

Two important factors that needs to be considered while design the biasing circuit which are responsible for shifting the operating point

i) Temperature ii) Variation of h_F (β) with manufacturer tolerance

Temperature:

The change in temperature effect the following parameters of the transistor. i) I_{CO} , ii) V_{BE} , iii) β_{AC}

The flow of current in the circuit provides heat at the junction. This heat produces temperature at the junction. We know that minority carriers are temperature dependent. They increase with temperature, the increase in minority carriers increases leakage current I_{CEO}

$$I_{CEO} = (1 + \beta) I_{CB0}$$

the efficiency. I_{CB0} doubles for every 10°C rise in temperature.

Increase in I_{CEO} in turn increases collector current

$$I_C = \beta I_B + I_{CEO}.$$

The increase in I_C further heats temperature at the collector junction and the same cycle repeats. The excessive increase in I_C shifts the operating point into the saturation region changing the operating condition set by biasing circuit.

As the power dissipated with in a transistor is predominantly the power dissipated at its collector base junction, the power dissipation is given as $P_D = V_C I_C$.

the increase

in collector current increases the power dissipated at the collector junction. This in turn further increases temperature of the junction and hence increases the collector current. The process is cumulative. The excess heat produced at the collector base junction may even burn and destroy the transistor. This situation is called thermal runaway of the transistor. For any transistor max power dissipation is always a fixed value this is known as max power dissipation rating of the transistor.

V_{BE} : V_{BE} changes with temperature at a rate of $2.5\text{mV}/^{\circ}\text{C}$.

base current I_B depends on V_{BE} and I_C depends on I_B , so

I_C depends on V_{BE} ; change of I_C changes the operating point.

$\underline{P_{dc}}$: P_{dc} is also temperature dependent. As P_{dc} varies, I_C also varies, since $I_C = \beta I_B$. Change of collector current changes the operating point.

Therefore to avoid such instability, the biasing circuit should be designed to provide a degree of temperature stability i.e. even though there are temperature changes, the changes in transistor parameters (V_{CEO} , I_{CO} , P_{max}) should be very less so that the operating point shifting is minimum in the middle of active region.

Variation of hFE (β) with manufacturers tolerance

at the manufacturing side of the transistor, the value of β may get varied from transistor to transistor. The biasing circuit is designed according to the required β value. But due to change in β from unit to unit, the operating point may shift.

Requirements of a biasing circuit:

- 1) The emitter-base junction must be forward biased (0.6V to 0.7V) and collector-base junction must be reverse biased (within max limits) i.e. transistor should be operated in middle of the active region (or) operating point (Q point) should be fixed at the center of the active region.
- 2) The circuit designed should provide a degree of temperature stability.
- 3) The operating point should be made independent of transistor parameters (such as β)

To maintain the operating point stable

by keeping SIC and V_{EE} constants so that the transistor will always work in active region, the following techniques are normally used.
i) Stabilization technique
ii) Compensation technique

Stabilizing techniques: Compensation techniques refer to the use of resistive biasing circuits which allow I_B to vary so as to keep I_C relatively constant with variations in I_{CEO} , β and V_{BE} .

Compensation techniques: These refer to the use of temperature sensitive devices such as diodes, transistors, thermistors, etc. which provide compensating voltages and currents to maintain the operating point stable.

Stability factors:

Stability factor, which indicates degree of change in operating point due to variation in temperature. Since there are three variables which are temperature dependent, we can define 3 stability factors.

$$i) S = \frac{\partial I_C}{\partial I_{CEO}} \quad (\text{or}) \quad S = \frac{\Delta I_C}{\Delta I_{CEO}} \quad | V_{BE}, \beta \text{ constant.}$$

$$ii) S' = \frac{\partial I_C}{\partial V_{BE}} \quad | I_{CEO}, \beta \text{ constant} \quad (\text{or}) \quad S' = \frac{\Delta I_C}{\Delta V_{BE}} \quad | I_{CEO}, \beta \text{ constant.}$$

$$iii) S'' = \frac{\partial I_C}{\partial \beta} \quad | I_{CEO}, V_{BE} \text{ constant} \quad (\text{or}) \quad S'' = \frac{\Delta I_C}{\Delta \beta} \quad | I_{CEO}, V_{BE} \text{ constant.}$$

for a CE configuration, current equation is given as

$$I_C = \beta I_B + I_{CEO} = \beta I_B + (1+\beta) I_{CB0}$$

when I_{CEO} changes by ΔI_{CEO} , I_B changes by ΔI_B and I_C changes by ΔI_C so

$$\Delta I_C = \beta \Delta I_B + (1+\beta) \Delta I_{CB0}$$

$$1 = \beta \frac{\Delta I_B}{\Delta I_C} + (1+\beta) \frac{\Delta I_{CB0}}{\Delta I_C} \Rightarrow$$

$$\frac{\Delta I_{CB0}}{\Delta I_C} = \frac{1-\beta \frac{\Delta I_B}{\Delta I_C}}{1+\beta} \Rightarrow S = \frac{1}{\frac{\Delta I_C}{\Delta I_C}} = \frac{1}{1-\beta \frac{\Delta I_B}{\Delta I_C}} = \frac{1+\beta}{1-\beta \frac{\Delta I_B}{\Delta I_C}}$$

The general procedure to obtain stability factor for various biasing circuits is as follows:

Step 1: Obtain the expression for I_B .

Step 2: Obtain $\frac{\partial I_B}{\partial I_C}$ and use it in Equation above to get S

Step 3: In standard equation of I_C , replace I_B in terms of V_{BE} to get S'

Step 4: Differentiate the equation obtained in step 3 w.r.t β to get

Stability factor for fixed bias Circuits:

$$I_B = \frac{V_{CC} - V_{BE}}{R_B} \approx \frac{V_{CC}}{R_B}$$

When I_B changes by ΔI_B , V_{CC} and V_{BE} are unaffected.

$\therefore \frac{\partial I_B}{\partial I_C} = 0 \quad \therefore I_C$ is not present in the equation

$$\Rightarrow S = \frac{1+\beta}{1-\beta(\frac{\partial I_B}{\partial I_C})} = \frac{1+\beta}{1-0} = 1+\beta \Rightarrow S = 1+\beta$$

Stability factor S'

$$S' = \left. \frac{\frac{\partial I_C}{\partial V_{BE}}}{I_C} \right|_{\text{IC0, } \beta \text{ Constants}} ; \text{ as we know } I_C = \beta I_B + (\beta+1) I_{CBO}$$

now representing I_B in terms of V_{BE} we get

$$I_C = \beta \left(\frac{V_{CC} - V_{BE}}{R_B} \right) + (\beta+1) I_{CBO} = \beta \frac{V_{CC}}{R_B} - \beta \frac{V_{BE}}{R_B} + (\beta+1) I_{CBO}$$

$$\frac{\frac{\partial I_C}{\partial V_{BE}}}{I_C} = 0 - \frac{\beta}{R_B} + 0 = -\frac{\beta}{R_B} \Rightarrow S' = -\frac{\beta}{R_B}$$

We know $S = 1+\beta$; $S' = -\beta/R_B$

$$\Rightarrow S' = -\frac{\beta(1+\beta)}{R_B(1+\beta)} \Rightarrow S' = -\frac{\beta S}{R_B(1+\beta)}$$

Stability factor $S'' = \frac{\partial I_C}{\partial \beta}$ | V_{BE}, I_{CO} constant.

as we know $I_C = \frac{\beta V_{CC}}{R_B} - \frac{\beta V_{BE}}{R_B} + (\beta+1) I_{CBO}$

$$\frac{\partial I_C}{\partial \beta} = \left(\frac{V_{CC}}{R_B} - \frac{V_{BE}}{R_B} \right) + I_{CBO} = I_B + I_{CBO} = \boxed{\frac{I_C}{\beta} = \frac{\partial I_C}{\partial \beta}}$$

since $\{ I_B = \frac{I_C}{\beta} \text{ and } I_B \gg I_{CBO} \}$

as we know $S = 1+\beta$; $S'' = \frac{I_C}{\beta} = \frac{I_C(1+\beta)}{\beta(1+\beta)} = \frac{I_C S}{\beta(1+\beta)}$

Different types of biasing Circuits:

Different types of biasing Circuits are

- i) Fixed bias Circuit
- ii) Collector to base bias Circuit
- iii) Voltage divider / Self bias Circuit
- iv) Emitter stabilized bias Circuit
- v) Miscellaneous bias Circuit

Fixed bias using a pnp transistor:

Here the voltage polarities and current directions are

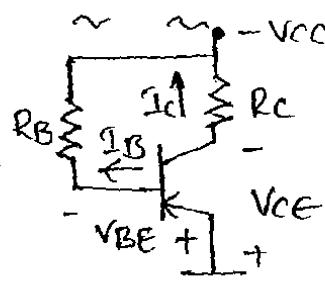
reversed than that of n-p-n transistor fixed bias

Circuit. However, the

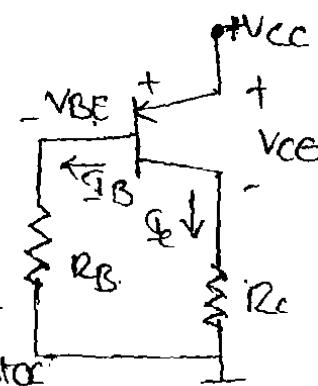
equations applied for the

analysis of n-p-n transistor fixed bias

Circuit can be applied for analysis of pnp transistor fixed bias Circuit.



fixed bias Circuit using pnp transistor



Another way of drawing fixed bias circuit using pnp

Transistor as a switch: Class A

- 1) This is a simple Ccircuit which uses very few components.
- 2) The operating point can be fixed anywhere on the active region of the characteristics by simply changing the value of R_B . Thus it provides max flexibility in the design.
- 3) This Ccircuit does not provide any check on the collector current which increases with rise in temperature, i.e. thermal stability is not provided by this Ccircuit. No operating point is not maintained. $I_C = \beta I_B + I_{CEO}$.
- 4) Since $I_C = \beta I_B$ and I_B is already fixed; I_C depends on β which changes unit to unit and shifts the operating point. So stabilization of operating point is very poor in fixed bias Ccircuit to Base bias Ccircuit:

The fig shows dc. bias with voltage feed back also called

Collector to base bias Ccircuit. It is an improvement over fixed bias method.

The biasing resistor is connected b/w collector and base of the transistor to provide a feed back path thus I_B flows through R_B and $(I_C + I_B)$ flows through R_C

Ccircuit Analysis:

Applying KVL at base we get

$$V_{CC} = (I_C + I_B)R_C + I_B R_B + V_{BE}$$

$$V_{CC} - V_{BE} = (1 + \beta) I_B R_C + I_B R_B$$

$$I_B = \frac{V_{CC} - V_{BE}}{R_B + (1 + \beta) R_C} = \frac{V_{CC} - V_{BE}}{R_B + \beta R_C}$$

$\beta \gg 1$

Note that the only difference b/w the equation for I_C and that obtained for the fixed bias configuration is the term βR_C , thus we can say that feed back path generates a reflection of the resistance R_C to the input circuit.

Applying Kirchhoff's law at the collector we get

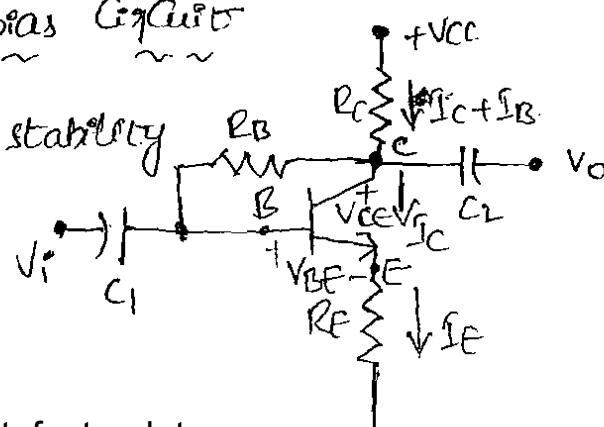
$$V_{CE} = (I_C + I_B)R_C \neq V_{CE} \Rightarrow V_{CE} = V_{CC} - (I_C + I_B)R_C$$

If there is a change in β due to piece to piece variation b/w transistor (or) if there is a change in β and I_{CO} due to change in temperature, then collector current I_C tends to increase, since $I_C = \beta I_B + I_{CO}$. As a result voltage drop across R_C increases, since V_{CC} is constant, hence V_{CE} reduces, due to decrease in V_{CE} , I_B reduces, as I_C depends on I_B , decrease of I_B reduces original increase in I_C . The result is that the circuit tends to maintain a stable value of collector current, keeping the Q point fixed.

In this circuit, R_B appears directly across input (base) and output (collector). A part of the output is fed back to the input, and increase in collector current decreases the base current. Thus -ve feed back exist in the circuit. So this circuit is also called voltage feedback bias circuit.

Modified collector to base bias circuit

To further improve level of stability the Emitter resistance is connected as shown.



Supplying the $\beta > 1$ to the equation

$$V_{CC} - (I_C + I_B)R_C - I_B R_B - V_{BE} - I_T R_E = 0.$$

$$V_{CC} - V_{BE} = (I_C + I_B)R_C + I_B R_B + (I_C + I_B)R_E$$

$$= (1 + \beta)I_B(R_C + R_E) + I_B R_B.$$

$$= I_B (R_B + (1 + \beta)(R_C + R_E))$$

$$\Rightarrow I_B = \frac{V_{CC} - V_{BE}}{R_B + (1 + \beta)(R_C + R_E)} = \frac{V_{CC} - V_{BE}}{R_B + \beta(R_C + R_E)} \quad \because \beta > 1$$

Note that only difference b/w equation for I_B and that obtained for fixed bias configuration is the term $\beta(R_C + R_E)$. thus we can say that the feed back path results in a reflection of the resistance R_C back to the collector circuit, much like reflection of R_E . In general we can say that

$$I_B = \frac{V'}{R_B + \beta R'} \quad \text{where } V' = V_{CC} - V_{BE}$$

$$\text{and } R' = 0 \text{ for fixed bias}$$

at collector circuit

$R' = R_E$ for Emitter bias

$$V_{CC} - (I_C + I_B)R_C - V_{CE} - I_E R_E = 0 \quad R' = R_C \text{ for collector to base bias}$$

$$V_{CE} = V_{CC} - I_E(R_C + R_E) \quad R' = R_C + R_E \text{ for collector to base bias with } R_E$$

Stability factor for collector to base bias circuit:

$$V_{CC} = I_C R_C + I_B (R_C + R_B) + V_{BE}$$

when I_{CBO} changes by ΔI_{CBO} , I_B changes by ΔI_B , and I_C changes by ΔI_C . There is no effect on V_{CC} & V_{BE} so

$$0 = \Delta I_C R_C + \Delta I_B (R_C + R_B) + 0 \Rightarrow \frac{\Delta I_B}{\Delta I_C} = -\frac{R_C}{R_C + R_B}$$

$$\text{as we know } S = \frac{1 + \beta}{1 - \beta(\Delta I_B / \Delta I_C)} = \frac{1 + \beta}{1 + \beta \cdot \frac{R_C}{R_C + R_B}}$$

Collector to base bias circuit is having lesser stability factor than - for fixed bias circuit, hence this circuit provides better stability than fixed bias circuit.

Stability factor = $\frac{\partial I_C}{\partial V_{BE}}$

The above equation shows that stability factor, S for the collector to base bias circuit also depends on β . If we design the circuit with condition $\beta R_C \gg R_B$ then we can make stability factor independent of β .

$$\text{as } S = \frac{1 + \beta}{1 + \beta \frac{R_C}{R_C + R_B}} = \frac{(1 + \beta)(R_C + R_B)}{R_C + R_B + \beta R_C} \approx \frac{(1 + \beta)(R_C + R_B)}{(1 + \beta)R_C} = \frac{R_C + R_B}{R_C}$$

and also we know that

$$I_C = (1 + \beta)I_{C0} + \beta I_B \Rightarrow I_B = \frac{I_C - (1 + \beta)I_{C0}}{\beta}$$

KVL at base of collector to base bias circuit

$$V_{CC} = (I_B + I_C)R_C + I_B R_B + V_{BE}$$

$$V_{CC} = I_B(R_C + R_B) + I_C R_C + V_{BE}$$

$$V_{CC} = \left[\frac{I_C - (1 + \beta)I_{C0}}{\beta} (R_C + R_B) + I_C R_C + V_{BE} \right]$$

$$\beta V_{CC} = I_C(R_C + R_B) - (1 + \beta)I_{C0}(R_C + R_B) + \beta I_C R_C + \beta V_{BE}$$

$$\beta V_{CC} + (1 + \beta)I_{C0}(R_C + R_B) - \beta V_{BE} = I_C(R_C + R_B + \beta R_C)$$

as $\beta \gg 1$; $\beta + 1 \approx \beta$.

$$I_C(R_B + \beta R_C) = \beta [V_{CC} - V_{BE} + I_{C0}(R_C + R_B)]$$

$$I_C \approx \frac{V_{CC} - V_{BE} + I_{C0}(R_C + R_B)}{R_C} \quad \because \beta R_C \gg R_B.$$

From above we can say that, the collector current has become independent of β and hence stabilized against changes in β .

Stability factors

$$S' = \left. \frac{\partial I_C}{\partial V_{BE}} \right|_{I_{C0}, \beta \text{ constants.}}$$

Applying KVL, $V_{CC} = (R_B + R_C)I_B + I_C R_C + V_{BE}$

$$V_C = V_{CC} - I_C R_C \Rightarrow \frac{I_C}{\beta} + \frac{I_B}{R_C + R_B} = \frac{V_{CC} - V_{BE}}{R_C + R_B}$$

$$I_C \left[\frac{R_C + R_B + \beta \frac{R_C}{\beta}}{\beta (R_C + R_B)} \right] = \frac{V_{CC} - V_{BE}}{R_C + R_B} \Rightarrow I_C = \frac{\beta (V_{CC} - V_{BE})}{R_B + (1+\beta) R_C}$$

$$\frac{\partial I_C}{\partial V_{BE}} = -\frac{\beta}{R_B + (1+\beta) R_C} \Rightarrow S' = -\frac{\beta}{R_B + (1+\beta) R_C}$$

Relation b/w S and S'

$$\text{we know } S = \frac{1+\beta}{1+\beta + \frac{R_C}{R_C + R_B}} \text{ and } S' = \frac{-\beta}{R_B + (1+\beta) R_C}$$

$$S = \frac{(1+\beta)(R_C + R_B)}{R_C + R_B + \beta R_C} = \frac{(1+\beta)(R_C + R_B)}{R_B + (1+\beta) R_C} \Rightarrow \frac{S}{(1+\beta)(R_C + R_B)} = -\frac{S'}{\beta}$$

$$\Rightarrow S' = -\frac{S\beta}{(1+\beta)(R_C + R_B)} ; \text{ if } S \text{ is small, } S' \text{ is still smaller}$$

If we provide stability against I_{CO} variations, we get stability against V_{BE} variations also

stability factor S'' :

$$S'' = \frac{\partial I_C}{\partial \beta} \Big|_{I_{CO}, V_{BE} \text{ Constant}}$$

for collector to base bias circuit we have,

$$V_{CC} - (I_C + I_B) R_C - I_B R_B - V_{BE} = 0$$

$$V_{CC} - V_{BE} = R_C (\beta I_B + I_B) + I_B R_B = I_B [R_B + (\beta + 1) R_C]$$

$$\Rightarrow I_B = \frac{V_{CC} - V_{BE}}{(\beta + 1) R_C + R_B} \Rightarrow I_C = \frac{\beta (V_{CC} - V_{BE})}{(1+\beta) R_C + R_B}$$

$$\frac{\partial I_C}{\partial \beta} = \frac{[(1+\beta) R_C + R_B] [V_{CC} - V_{BE}] - \beta [V_{CC} - V_{BE}] (R_C)}{[(1+\beta) R_C + R_B]^2}$$

$$= \frac{(V_{CC} - V_{BE}) ((1+\beta) R_C + R_B - \beta R_C)}{[(1+\beta) R_C + R_B]^2} = \frac{(V_{CC} - V_{BE})(R_C + R_B)}{[(1+\beta) R_C + R_B]^2}$$

$$\frac{V_C - V_B}{(1+\beta)R_C + R_B} = \frac{\beta \times (R_{E2} + R_E)}{\beta^2 ((1+\beta)R_C + R_B)}$$

as we know $S'' = \frac{I_C (R_B + R_C)}{\beta [(1+\beta)R_C + R_B]} = \boxed{\frac{I_C S}{\beta (1+\beta)} = S''}$

Voltage divided base / self bias circuit

The biasing is provided by three resistors

R_1 , R_2 , and R_E . The resistors R_1 and R_2 acts as potential divider giving a fixed value to point 'B' which is Base.

If collector current increases due to change in temperature (or) change in β the emitter current I_E also increases. and voltage drop across R_E increases, reducing

voltage difference b/w base & Emitter (V_{BE}). due to reduction in V_{BE}, base current I_B hence collector current I_C also reduces. so therefore we say that -ve feedback exists in the Emitter bias circuit. this reduction in collector current I_C compensates for original change in I_C.

Circuit Analysis:

Voltage across R_2 is the base voltage V_B.

Applying the voltage divider theorem to find V_B,

we get $V_B = \frac{R_2 \Sigma}{R_1 (I + I_B) + R_2 (\Gamma)} \times V_{CC}$

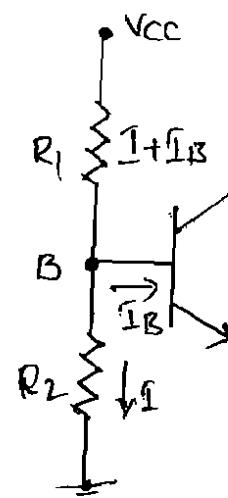
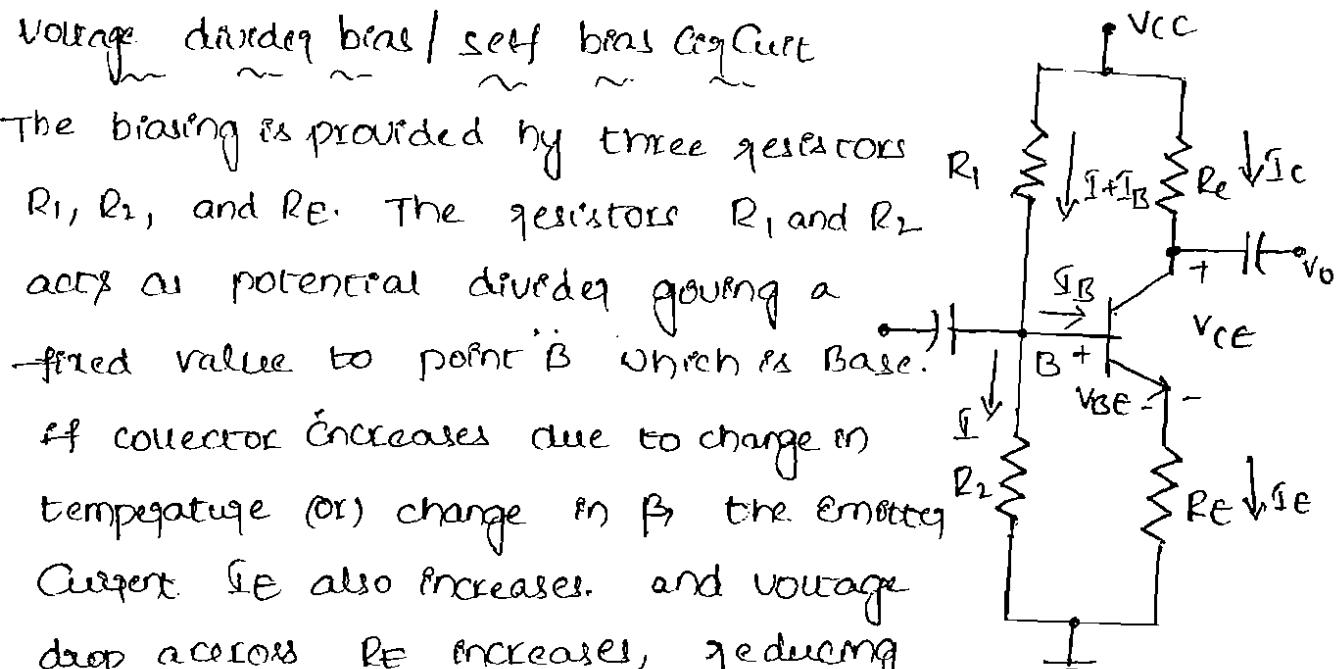
as $I \gg I_B$ $V_B = \frac{R_2}{R_1 + R_2} \times V_{CC}$

applying KVL at collector circuit we get

$$V_{CC} - I_C R_C - V_{CE} - I_E R_E = 0$$

$$V_{CE} = V_{CC} - I_C R_C - I_E R_E ; V_E = I_E R_E = V_B - V_{BE}$$

$$\frac{I_E}{I_C} = \frac{V_B - V_{BE}}{R_E}$$



Dependence of output voltage on biasing

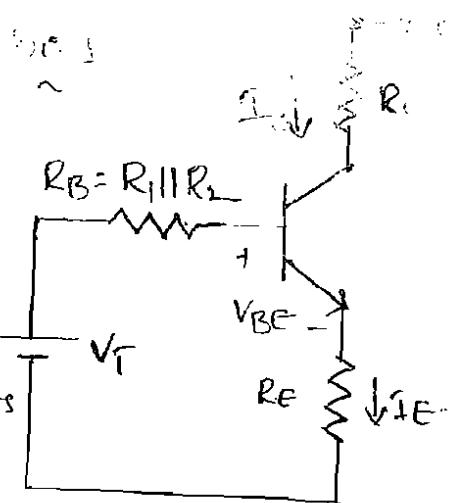
The circuit shows simplified effect of voltage divider bias. Here R_1 and R_2 are replaced by R_B and V_T , where R_B is the parallel combination of R_1 & R_2 and V_T is the Thvenin's voltage. R_B is

$$R_B = \frac{R_1 R_2}{R_1 + R_2}; \text{ KVL at base of the}$$

$$\text{circuit} \quad V_T = I_B R_B + V_{BE} + I_E R_E$$

$$V_T = I_B R_B + I_B R_E + I_C R_E + V_{BE}$$

$$\Rightarrow V_{BE} = V_T - (R_B + R_E) I_B - I_C R_E$$



Thevenin's equivalent circuit for voltage

Stability factor for voltage divider bias

$$\text{Here } V_T = \frac{R_2 \times V_{CC}}{R_1 + R_2}; \quad R_B = \frac{R_1 R_2}{R_1 + R_2}$$

at base circuit we have

$$V_T = I_B R_B + V_{BE} + (I_B + I_C) R_E$$

differentiating w.r.t I_C and considering

V_{BE} to be independent of I_C , we get

$$0 = \frac{\partial I_B}{\partial I_C} R_B + \frac{\partial I_B}{\partial I_C} R_E + R_E \Rightarrow \frac{\partial I_B}{\partial I_C} = - R_E / (R_B + R_E)$$

as we know $S = 1 + \beta$

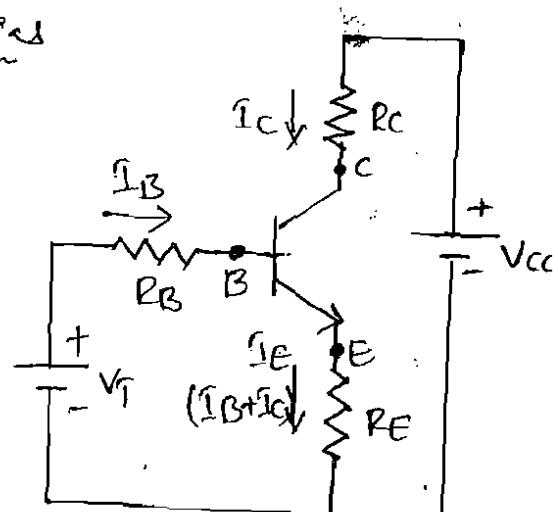
$$S = \frac{1 + \beta}{1 + \beta \frac{\partial I_B}{\partial I_C}} = \frac{1 + \beta}{1 + \beta \frac{R_E}{R_B + R_E}} = \frac{1 + \beta (R_B + R_E)}{R_B + (1 + \beta) R_E}$$

$$S = (1 + \beta) \left(1 + \frac{R_B}{R_E} \right) / \left(1 + \beta + \frac{R_B}{R_E} \right)$$

the ratio of R_B/R_E controls the value of stability factors.

If $R_B/R_E \ll 1$ then $S = \frac{(1 + \beta)}{(1 + \beta)} = 1$ practically $R_B/R_E \neq 0$

but to have better stability factor's we have to keep ratio of R_B/R_E as small as possible.



3) To C.E. R_B/R_2 small, it is necessary to keep it small, this means that R_B/R_2 must be small. Due to parallel small values of R_1 & R_2 , potential divider circuit will draw more current from V_{cc} reducing life of battery. So while designing if we make R_2 much smaller than R_1 then parallel combination gives us small R_B without drawing more current through V_{cc}. Reducing R_B will reduce I_p impedance of the circuit, since R_B comes in parallel with I_p. This is not desirable in Amplifreq Circuits hence R_B cannot be made very small.

4) Emitter resistance R_E is the another parameter, used to decrease ratio of R_B/R_E , by increasing R_E . But as we increase R_E , drop $I_E R_E$ will also increase and since V_{cc} is constant, drop across R_C will reduce, thus shifts the operating point which is not desirable hence there is limit of increasing of R_E .

So the compromising value are

S - Small, $R_B \rightarrow$ Reasonably small, $R_E \rightarrow$ not very large

5) If ratio of R_B/R_E is fixed, S increases with β so stability decreases with increasing β . S is essentially independent of β for small values of S.

Stability factor S'

Stability factor S' is given by

$$S' = \frac{\partial I_C}{\partial V_{BE}} \Big|_{I_C \text{ constant}, \beta \text{ constant}}$$

We know that

$$I_C = (1+\beta) I_{C0} + \beta I_B$$

$$\text{and } V_T = I_B R_B + V_{BE} + (I_B + I_C) R_E$$

$$\Rightarrow V_{BE} = V_T - (R_E + R_B) I_B - R_E I_C$$

$\frac{d}{dt} \phi(t) = \int_{\mathbb{R}^n} \phi(t) \cdot \nabla \phi(t) + \left(\frac{1}{2} |\nabla \phi|^2 - V(x) \right) \phi(t)$

Substituting A.B., we get

$$\begin{aligned}
 VBE &= V_T - (R_E + R_B) \left[\frac{\frac{I_C}{\beta} - (1+\beta)I_{CO}}{R_S} \right] - R_E I_C \\
 &= V_T - \frac{(R_E + R_B)I_C}{\beta} + \frac{(1+\beta)(R_E + R_B)}{\beta} I_{CO} - R_E I_C \\
 &= V_T - \left[\frac{(1+\beta)R_E + R_B}{\beta} \right] I_C + \frac{(R_E + R_B)(1+\beta)}{\beta} I_{CO}.
 \end{aligned}$$

differentiating above equation w.r.t VBE with I_{CO} and β constant, we get

$$I = 0 - \frac{(1+\beta) R_E + R_B}{\beta} \frac{\partial I_C}{\partial V_{BE}} \Rightarrow \frac{\partial I_C}{\partial V_{BE}} = -\beta / R_B + (1+\beta) R_E$$

$$\Rightarrow S' = -\beta / R_B + (1+\beta) R_E$$

Relation between s and s'

$\sim \sim \sim \sim \sim$ we know that

$$S = (1+\beta) \frac{1 + R_B / R_E}{1 + \beta + R_B / R_E} = \frac{(1+\beta)(R_E + R_B)}{(1+\beta)R_E + R_B}$$

$$\Rightarrow \frac{S}{(1+\beta)(R_E + R_B)} = -\frac{1}{R_B + (1+\beta)R_E}$$

$$\Rightarrow S^I = -\beta \times \frac{S}{(1+\beta)(R_E+R_B)} + -\frac{S}{(R_E+R_B)} \times \frac{\beta}{1+\beta}.$$

If value of β is lower, leads to lowering value of S . Thus as we reduce β towards unity, we minimize the change of S with respect to both, V_{BE} and I_{CO} .

Stability factor S'

S'' is given by $S'' = \frac{\partial Ic}{\partial V} \Big|_{Ic=VBE \text{ Constant}}$

$$\text{we know that } V_{BE} = V_T - \frac{[R_B + (1+\beta) R_E] I_C}{\beta} + \left[\frac{(R_E + R_B)(1+\beta)}{\beta} \right] I_{CO}$$

$$V_{BE} = V_T - \frac{R_B + (1+\beta) R_E}{\beta} I_C + V$$

$$V' = \frac{(R_B + R_E)(1+\beta)}{R_E} I_{CO} \approx (R_B + R_E) I_{CO} \quad \because \beta \gg 1$$

$$\Rightarrow I_C = \beta(V_T + V' - V_{BE}) / (R_B + R_E(1+\beta))$$

Differentiating above equation w.r.t β and V' independent of β
we get

$$\frac{\partial I_C}{\partial \beta} = \frac{[R_B + R_E(1+\beta)][V_T + V' - V_{BE}] - \beta[V_T + V' - V_{BE}]R_E}{[R_B + R_E(1+\beta)]^2}$$

$$= \frac{(V_T + V' - V_{BE})[R_B + R_E] \times (1+\beta)}{(1+\beta)[R_B + R_E(1+\beta)][R_B + R_E(1+\beta)]} = \frac{S(V_T + V' - V_{BE})}{(1+\beta)[R_B + R_E(1+\beta)]}$$

$$\text{Since } S = (1+\beta)(R_E + R_B) / (R_B + (1+\beta)R_E)$$

$$\frac{\partial I_C}{\partial \beta} = \beta S (V_T + V' - V_{BE}) / \beta(1+\beta)(R_B + R_E(1+\beta)) = \frac{I_C S}{\beta(1+\beta)}$$

$$\text{Since } I_C = \beta(V_T + V' - V_{BE}) / [R_B + R_E(1+\beta)]$$

$$S'' = \frac{\partial I_C}{\partial \beta} = \frac{I_C S}{\beta(1+\beta)}$$

Thus, the change in collector current due to change in β is

$$\Delta I_C = S'' \Delta \beta = \frac{I_C S}{\beta(1+\beta)} \Delta \beta$$

where $\Delta \beta = \beta_2 - \beta_1$ may represents a large change in β . Hence it is not clear whether to use β_1, β_2, S'' is obtained by taking finite differences rather than by evaluating a derivative.

$$\text{thus } S'' = \frac{\partial I_C}{\partial \beta} = \frac{I_{C2} - I_{C1}}{\beta_2 - \beta_1}; \text{ we know that } I_C = \beta \frac{(V_T + V' - V_{BE})}{R_B + R_E(1+\beta)}$$

$$\frac{I_{C2}}{I_{C1}} = \frac{\beta_2[R_B + R_E(1+\beta_1)]}{\beta_1[R_B + R_E(1+\beta_2)]}$$

$$\frac{I_{C2} - I_{C1}}{I_{C1}} = \frac{\beta_2[R_B + R_E(1+\beta_1)] - \beta_1[R_B + R_E(1+\beta_2)]}{\beta_1[R_B + R_E(1+\beta_2)]}$$

$$\frac{\partial I_C}{I_C} = \frac{\beta_2 R_B + \beta_2 R_E + \beta_1 \beta_2 R_E - \beta_1 R_B - \beta_1 R_E - \beta_1 \beta_2 R_E}{\beta_1[R_B + R_E(1+\beta_2)]}$$

$$= \frac{\beta_2 - \beta_1}{\beta_1} \frac{(R_B + R_E)}{R_B + R_E(1+\beta_2)} = \frac{\Delta \beta}{\beta_1} \frac{R_B + R_E}{R_B + R_E(1+\beta_2)}$$

$$\frac{I_1}{I_B} = \frac{I_C}{I_B} = \frac{I_E}{I_B} \cdot \frac{(1+\beta)}{(1+\beta)R_E + R_B}$$

$$S' = \frac{\partial I_C}{\partial \beta} = \frac{I_C}{I_B} \times \frac{\beta_2}{(1+\beta_2)} \quad \text{since } S_2 = S = \frac{(1+\beta)(R_E + R_B)}{R_B + (1+\beta)R_E}$$

Emitter stabilized bias Circuit:

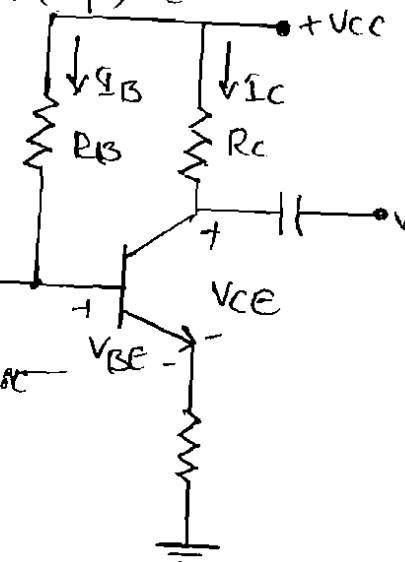
To improve the stability of the biasing

Circuit over the fixed bias Circuit,

the emitter resistance is connected

in the biasing circuit. Such biasing circuit

is known as Emitter bias Circuit.



Circuit analysis:

Applying KVL at the base of the circuit, we get

$$V_{CC} - I_B R_B - V_{BE} - I_E R_E = 0; \text{ we know that } S_E = (1+\beta) I_B.$$

$$\Rightarrow V_{CC} - V_{BE} = I_B R_B + (1+\beta) I_E R_E \Rightarrow I_B = \frac{V_{CC} - V_{BE}}{R_B + (1+\beta) R_E}$$

as $\beta \gg 1$

$$\Rightarrow I_B = \frac{V_{CC} - V_{BE}}{R_B + \beta R_E}$$

Note that the only difference b/w the equation for I_B and that obtained for the fixed bias configuration is the term βR_E .

Applying KVL at collector Circuit we get

$$V_{CC} - I_C R_C - V_{CE} - I_E R_E = 0 \Rightarrow$$

$$V_C = V_{CC} - I_C R_C; V_E = I_E R_E; V_{CE} = V_C - V_E$$

The addition of the emitter resistance R_E in the emitter bias circuit provides improved stability, i.e. the bias d.c. bias currents and voltages remains closer to where they were set by the circuit against the changes in temperature and transistor β .

Moderate bias configuration

In this biasing, the biasing does not depend on basic biasing configurations.

as emitter base junction is forward biased. assume transistor is in active region

Applying KVL at base we get

$$-V_{EE} = I_B R_B + V_{BE} \text{act} + I_E R_E$$

$$\Rightarrow 10 = I_B R_B + V_{BE} \text{act} + (1+\beta) I_B R_E \Rightarrow 10 - 0.7 = 270 \times 10^3 I_B + 101 \times 10^3 I_B$$

$$\Rightarrow 9.3 = 371 \times 10^3 I_B \Rightarrow I_B = \frac{9.3}{371 \times 10^3} = 25.067 \mu\text{A}$$

Applying KVL at collector we get

$$-V_{EE} = I_C R_C + V_{CE} \text{act} + I_E R_E$$

$$= \beta I_B R_C + V_{CE} \text{act} + (1+\beta) I_B R_E$$

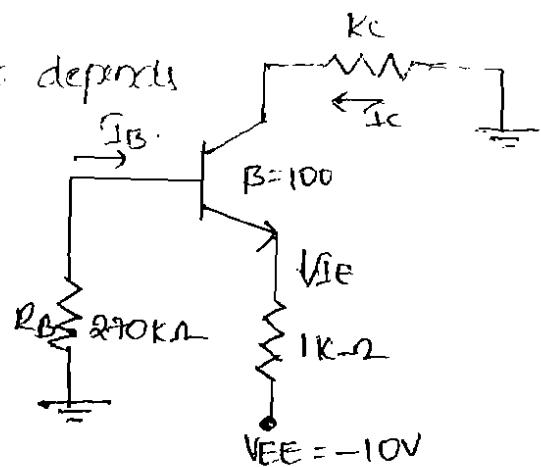
$$10 = 100 \times 25.067 \times 10^{-6} \times 10^3 + V_{CE} \text{act} + (1+100) \times 25.067 \times 10^{-6} \times 10^3$$

$$\Rightarrow V_{CE(\text{act})} = 4.961 \text{ V}$$

$$\text{and } I_C = \beta I_B = 100 \times 25.067 \times 10^{-6} = 2.5067 \text{ mA}$$

Bias compensation using diodes and transistors

The biasing circuits so far discussed provide stability of operating point in case of variations in the transistor parameters such as I_{CO} , V_{BE} and β . the collector to base bias and the voltage follower bias use the -ve feed back to do the stabilization action. this -ve feed back reduces the amplification of the signal. if this loss in signal amplification is intolerable and extremely stable biasing conditions are required, then it is necessary to use compensation techniques. there are temperature sensitive devices such as diodes, transistors, thermistors, etc.



Work on Biased Transistor

compensation for V_{BE} :

a) Diode in Emitter Circuit:

The circuit shows the voltage divider bias with bias compensation technique.

Here separate supply V_D is used to keep diode in forward biased condition if the diode used

in the circuit is of same material and the type as transistor, the voltage across the diode will have same temperature coefficient ($-2.5 \text{ mV}/^\circ\text{C}$) as the base to emitter voltage V_{BE} . So when V_{BE} changes by ΔV_{BE} with change in temperature, V_D changes by ΔV_D and $\Delta V_D \approx \Delta V_{BE}$, the changes tend to cancel each other.

Applying KVL to the base we get

$$V_T = I_B R_B + V_{BE} + (I_C + I_B) R_E - V_D \\ = I_B (R_B + R_E) + V_{BE} + I_C R_E - V_D$$

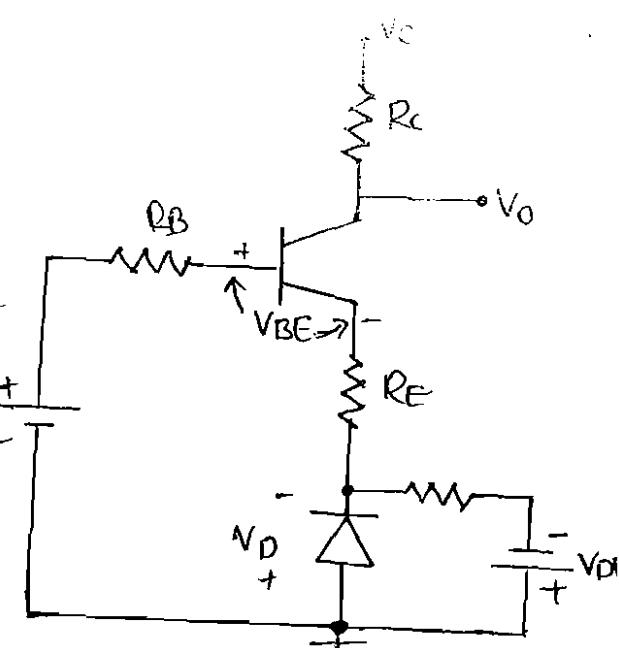
by considering leakage current we have

$$I_C = \beta I_B + (1+\beta) I_{CO} \Rightarrow I_B = \frac{I_C}{\beta} + \frac{(1+\beta) I_{CO}}{\beta}$$

$$V_T = \left[\frac{I_C}{\beta} + \frac{(1+\beta) I_{CO}}{\beta} \right] (R_B + R_E) + I_C R_E + V_{BE} - V_D \\ = \frac{I_C}{\beta} [(R_B + R_E)] + \frac{\beta I_C R_E}{\beta} + \frac{(1+\beta)}{\beta} I_{CO} (R_B + R_E) + V_{BE} - V_D \\ = \frac{I_C}{\beta} [R_B + (1+\beta) R_E] + \frac{(R_B + R_E)(1+\beta) I_{CO}}{\beta} + V_{BE} - V_D$$

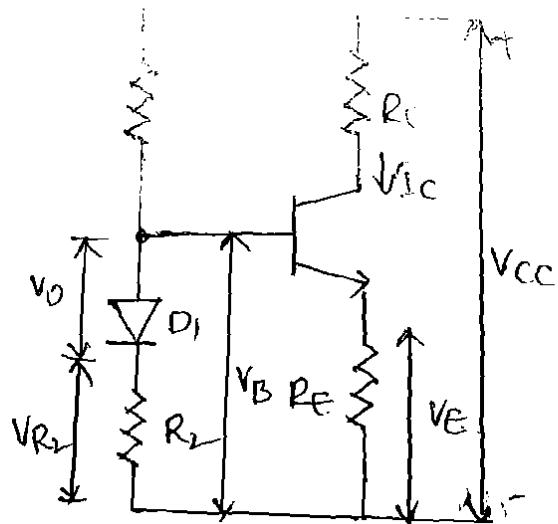
$$\Rightarrow I_C = \frac{\beta [V_T - (V_{BE} - V_D)] + (R_B + R_E)(1+\beta) I_{CO}}{R_B + (1+\beta) R_E}$$

Since V_D traces V_{BE} with respect to temperature, it is clear that I_C will be constant with variations in V_{BE} .



During low voltage biasing method

fig. shows diode compensation technique used in voltage divider bias. Here, diode D_1 is connected in parallel with R_2 in voltage divider circuit and it is forward biased condition.



$$\text{we know that } I_E = \frac{V_B - V_{BE}}{R_E} = \frac{V_F}{R_E} \quad \text{since } I_C \approx I_E$$

$$\Rightarrow I_C \approx I_E = \frac{V_B - V_{BE}}{R_E}$$

When V_{BE} changes with temperature, I_C also changes. To cancel the change in I_C , one diode is used in this circuit for compensation. The voltage at V_B is given as

$$V_B = V_{R2} + V_D ; \Rightarrow I_C \approx I_E = \frac{V_{R2} + V_D - V_{BE}}{R_E}$$

If the diode which is used in this circuit is of same material and type as transistor, the voltage across the diode will have same temperature coefficient ($-2.5 \text{ mV}/\text{°C}$) as the base to emitter voltage V_{BE} . so when V_{BE} changes by ΔV_{BE} with change in temperature, V_D changes by ΔV_D and $\Delta V_D = \Delta V_{BE}$ the changes tend to cancel each other and leave the

Collector current as $I_C = \frac{V_{R2}}{R_E}$ which is unaffected due to change in V_{BE} . From fig. we can see that biasing is provided by R_1 , R_2 and R_E . The changes in V_{BE} due to temperature are compensated by changes in diode voltage which keeps I_C stable at a point.

- Output due to T_C .

In case of Ge transistors, changes in I_{CO} with temperature are comparatively larger than Silicon transistor. Hence in Ge changes of I_{CO} with temperature play a vital role in collector current stability than changes in V_{BE} .

The diode is kept in reverse bias, the diode has the only leakage current. If the diode and the transistor are of same type and material, the leakage current I_0 , will increase with temperature at the same rate as the collector leakage current from above fig $I = \frac{V_{CC} - V_{BE}}{R_1}$; $I = I_B + I_0 \Rightarrow I_B = I - I_0$

for 'Ge', $V_{BE} = 0.2\text{ V}$ which is very small, and neglecting change in V_{BE} with temperature we can write

$$I = V_{CC} / R_1 \approx \text{Constant}; \text{ we know that } I_C = \beta I_B + (1 + \beta) I_{CO}.$$

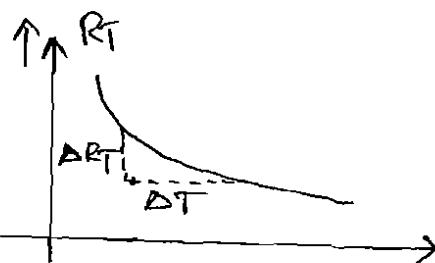
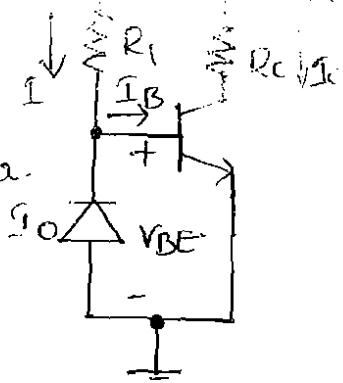
$$\Rightarrow I_C = \beta I - \beta I_0 + (1 + \beta) I_{CO} \quad \beta \gg 1 \Rightarrow I_C = \beta I - \beta I_0 + \beta I_{CO}.$$

If $I_0 = I_{CO} \Rightarrow I_C = \beta I$; As I is constant, I_C remains fairly constant \Rightarrow changes by I_{CO} with temperature are compensated by diode and collector current remains fairly constant.

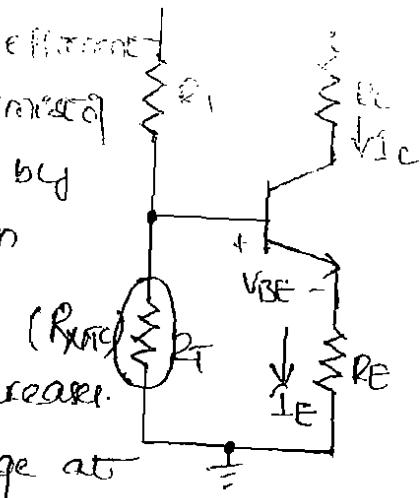
Thermistor Compensation:

The method of transistor compensation uses temperature sensitive elements, thermistors rather than diodes (or) transistors. It has Temperature Vs R_T a negative temperature coefficient, its resistance of thermistor decreases exponentially with increasing temperature.

$$\text{Slope of the curve} = \frac{\partial R_T}{\partial T} \quad (\text{temperature coefficient for thermistor})$$



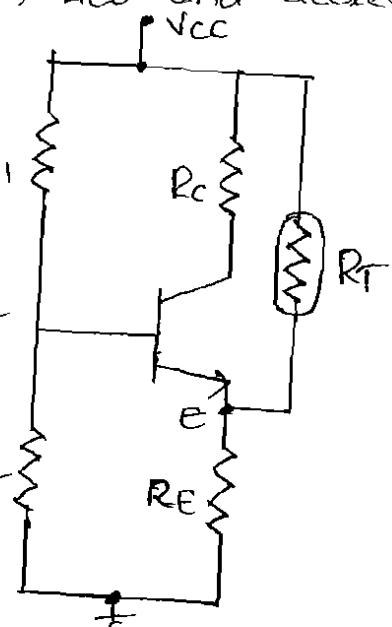
The thermistor has +ve temperature coefficient of resistance. The next fig shows thermistor compensation technique; R_1 is replaced by thermistor R_T in Self bias circuit. With increase in temperature, R_T decreases. Hence voltage drop across it also decreases. This voltage is nothing but the voltage at the base w.r.t ground. Hence V_{BE} decreases which reduces I_B . This behaviour will tend to offset the increase in collector current with temperature.



$$I_C = \beta I_B + (1 + \beta) I_{CO}$$

In above equation, there is increase in I_{CO} and decrease in I_B which keeps I_C almost constant.

The next fig shows another transistor compensation technique. The thermistor is connected b/w emitter and V_{CC} to minimize the increase in collector current due to changes in I_{CO} , V_{BE} (or) β . With temperature, R_2 increases with temperature and R_T decreases with increase of temperature.



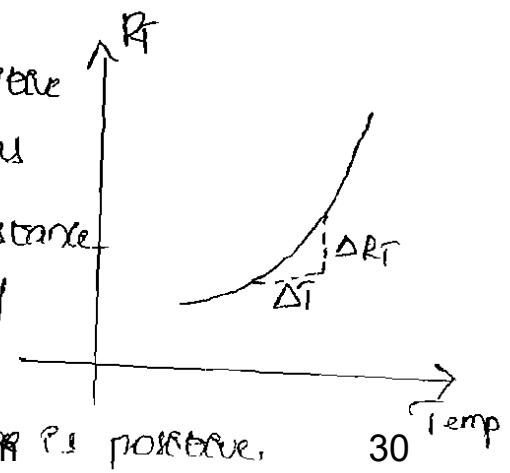
so current flowing through R_E increases. E-B junction is forward biased, hence V_{BE} reduces, so base current reduces.

Transistor Compensation Technique:

This technique uses temperature sensitive resistive element, thermistor, which has +ve temperature coefficient, its resistance increases exponentially with increase of temperature.

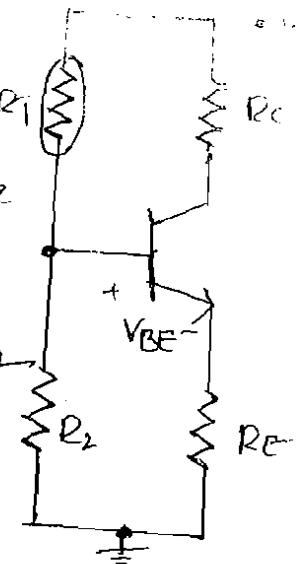
$$\text{slope of curve} = JR_T$$

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the bias voltages for voltage compensation. Example.

R_1 and R_2 forms the collectors of potential divider network. With increase of temperature R_T also increases which decreases current flowing through it. Hence current through R_2 decreases which decreases voltage at R_2 i.e. V_{BE} , hence I_B decreases, and hence I_C remains fairly constant.



Thermal runaway:

The max avg. power $P_D(\max)$ which a transistor can dissipate depends up on the transistor construction and lie in the range of few milliwatts to 200 μ w as mentioned earlier. The power dissipated with in a transistor is predominantly the power dissipated at the collector base junction. Thus max power is limited by the temperature that the collector base junction can withstand. For Si it is range of 150 to 200°C, for Ge -60° to 100°C the collector base junction temperature may rise because of two reasons. i) Due to rise in ambient temperature ii) Due to self heating.

The increase in the collector current increases the power dissipated at the collector junction. This, in turn further increases the temperature of the junction and hence increase in collector current the process is cumulative and it is referred to as a self heating. The excess heat produced at the collector base junction may even burn and destroy the transistor. The situation is called thermal runaway of the transistor.

It is necessary to avoid thermal runaway which may even burn and destroy transistor. To avoid thermal runaway, the rate at which heat is released at the collector junction must not exceed the rate at which heat can be dissipated.

The temperature rise at collector junction is proportional to the power dissipated at the junction.

$$\Theta = T_J - T_A = \theta P_D ; \quad T_J \rightarrow \text{Junction temperature in } ^\circ\text{C}$$

$T_A \rightarrow$ Ambient temperature in $^\circ\text{C}$. $P_D \rightarrow$ power dissipation at

$\theta \rightarrow$ Constant of proportionality, collector junction.

$\theta \rightarrow$ also referred as thermal resistance.

$$\theta = T_J - T_A / P_D ; \quad \text{unit of } \theta \text{ is } ^\circ\text{C}/\text{watt}$$

The maximum collector power P_c allowed for safe operation is specified at 25°C

To avoid thermal runaway $\frac{\partial P_c}{\partial T} < \frac{\partial P_D}{\partial T}$

$$\text{as we know } T_J - T_A = \theta P_D \Rightarrow I = \theta \cdot \frac{\partial P_D}{\partial T}$$

$$\Rightarrow \frac{\partial P_D}{\partial T} = \gamma \theta \Rightarrow \frac{\partial P_c}{\partial T} < \frac{1}{\theta}$$

By properly designing a heatsink or fin it is possible to ensure that transistor cannot runaway below a specified ambient temperature (α) even under any condition.

for voltage divider bias circuit

$P_c =$ heat generated at collector junction

= d.c. power dissipated to the circuit - power loss as $I^2 R$ in R_C & R_E

$$P_c = V_{CC} I_C = I_C^2 R_C + I_E^2 R_E ; \quad \text{as } I_C \approx I_E$$

$$\therefore P_0 P_c = V_{CC} I_C - I_C^2 (R_C + R_E)$$

$\frac{\partial I_C}{\partial T_j} = \text{constant} + (\beta_0 + \beta_1 T_j)$, as we know $\frac{\partial I_C}{\partial T_j} = \frac{\partial I_C}{\partial T_i} \frac{\partial T_i}{\partial T_j}$.

$\frac{\partial I_C}{\partial T_j}$ can be written as $= S \frac{\partial I_C}{\partial T_j} + S' \frac{\partial V_{BE}}{\partial T_j} + S'' \frac{\partial \beta}{\partial T_j}$ since generation

temperature affects collector current by affecting I_{CO} , V_{BE} and β .
but as we are doing analysis for thermal runaway, I_{CO} dominates. so $\frac{\partial I_C}{\partial T_j} = \frac{\partial I_{CO}}{\partial T_j}$

As reverse saturation current for both 'si' & 'ge' increased about 7% per $^{\circ}\text{C}$ rise, we get $\frac{\partial I_{CO}}{\partial T_j} = 0.07 I_{CO}$.

$$\Rightarrow \frac{\partial I_C}{\partial T_j} = S \times 0.07 I_{CO} \Rightarrow [V_{CE} - 2I_C(R_C + R_E)] S(0.07 I_{CO}) < 0$$

as 'S', I_{CO} and α are positive, to satisfy above eq.

$$V_{CC} < 2I_C(R_C + R_E) \Rightarrow \frac{V_{CC}}{2} < I_C(R_C + R_E)$$

Applying KVL to the collector leg of voltage divider bias configuration we get

$$V_{CE} = V_{CC} - I_C(R_E + R_C) \because I_C \approx I_E$$

$$\Rightarrow I_C(R_E + R_C) = V_{CC} - V_{CE} \Rightarrow \frac{V_{CC}}{2} < V_{CE} - V_{CE} \Rightarrow V_{CE} < \frac{V_{CC}}{2}$$

thus if $V_{CE} < \frac{V_{CC}}{2}$, the stability is ensured. but in transformer coupled oscillators, R_C & R_E are small hence $V_{CE} \approx V_{CC}$. so it is necessary to design transformer coupled oscillators with stability factor as close to 1 as possible to avoid thermal runaway.

f) Fixed biasing

In FET's as temperature increases drain resistance also increases, so that reduction of drain current takes place. However, the wide differences in maximum and minimum transfer characteristics make it necessary to keep drain current I_D stable at its quiescent value.

$$\text{as we know } I_D = I_{DSS} \left[1 - \frac{V_{GS}}{V_p} \right]^2$$

different biasing techniques of FET are

- i) Fixed bias Circuit
- ii) Self bias Circuit
- iii) voltage divider bias

The below fig shows fixed bias circuit which is completed a separate supply V_{GG} is connected such that gate is made negative than source. the current through R_g is $I_g = 0$.

S1: calculate V_{GS} :

$$\text{for d.c. analysis } I_g = 0 \Rightarrow V_{GS} = -V_{GG}$$

since V_{GG} is fixed in magnitude, hence the voltage V_{GS} is also fixed.

S2: Calculate I_{DQ} :

I_D can be calculated by using

$$I_{DQ} = I_{DSS} \left[1 - \frac{V_{GS}}{V_p} \right]^2$$

S3: calculate V_{DS} :

By law of drain, we get

$$V_{DD} - I_D R_D - V_{DSQ} = 0$$

$$\Rightarrow V_{DSQ} = V_{DD} - I_D R_D$$

The main draw back of fixed bias circuit is it requires two power supplies.

Voltage Divider Bias Circuit

The voltage at the source of the JFET must be more positive than the voltage at the gate in order to keep the gate-source junction reverse biased. The source voltage is $V_s = I_D R_s$.

The gate voltage is set by resistors R_1 and R_2 . Coupling capacitors C_1 and C_2 and source resistor R_s , bypass capacitor C_b are assumed to be open circuit for D.C. analysis.

D.C. analysis:

$$S1: \text{ Calculate } V_g = \frac{V_{DD} R_2}{R_1 + R_2} \quad \because S_g = 0.$$

S2: obtain expression for V_{GS} .

Applying KVL to the top of one we get

$$V_g - V_{GS} - I_D R_s = 0 \Rightarrow V_{GS} = V_g - I_D R_s.$$

$$S3: \text{ calculate } I_{DQ} = I_{DSs} \left[1 - \frac{V_{GS}}{V_p} \right]^2$$

S4: calculate V_{DS} and V_{GS} .

Applying KVL at the dp of one we get

$$V_{DD} - I_D R_D - V_{DS} - I_D R_s = 0.$$

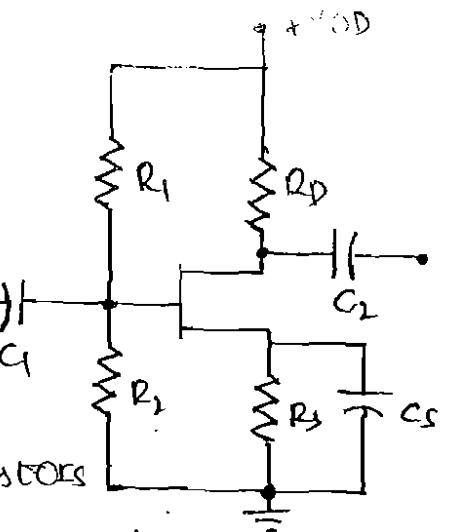
$$\Rightarrow V_{DS} = V_{DD} - I_D R_D - I_D R_s = V_{DD} - I_D (R_D + R_s)$$

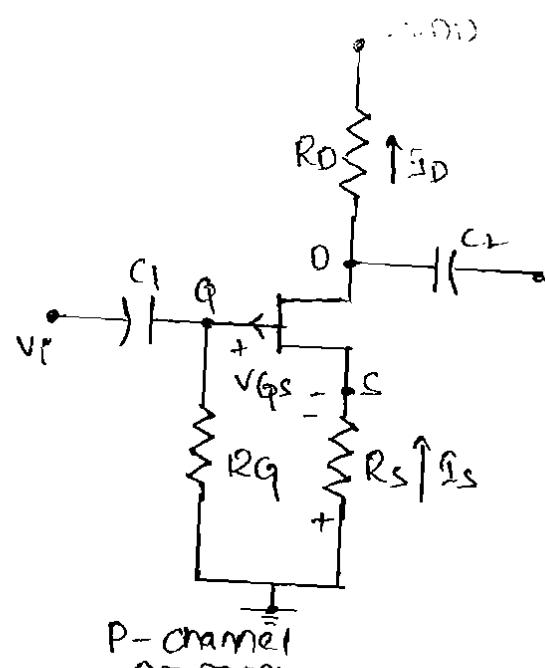
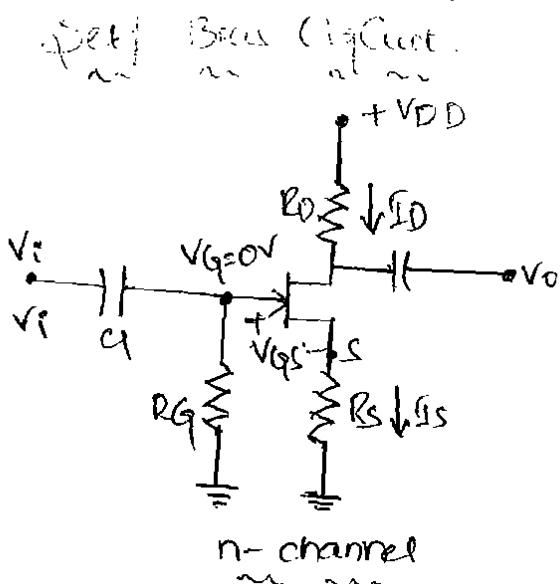
The Q-point of a JFET amplifier using voltage divider bias is

$$I_{DQ} = I_{DSs} \left[1 - \frac{V_{GS}}{V_p} \right]^2$$

$$V_{DSQ} = V_{DD} - I_D (R_D + R_s)$$

$$V_{GSQ} = V_g - I_D R_s.$$





JFET must be operated such that the gate source junction is always reverse biased. This requires a -ve V_{GS} for an n-channel JFET and a positive V_{GS} for p-channel JFET. The gate resistor, R_G , does not affect the bias because it has essentially no voltage drop across i_D . So the gate polarization R_G is necessary only to isolate an a.c. signal from ground in amplifier applications. The voltage drop across, R_S make gate source junction reverse biased.

D.C. analysis:

S1: obtain Expression for V_{GS} :

as I_S produces a voltage drop across R_S , and $I_S = I_D$ and $V_G = 0$
then $V_S = I_S R_S = I_D R_S \Rightarrow V_{GS} = V_G - V_S = 0 - I_D R_S = -I_D R_S$.

S2: Calculate I_{DQ}

$$I_D = I_{DSS} \left[1 - \frac{V_{GS}}{V_P} \right]^2 = I_{DSS} \left[1 + \frac{I_D R_S}{V_P} \right]^2$$

S3: calculate V_{DS} .

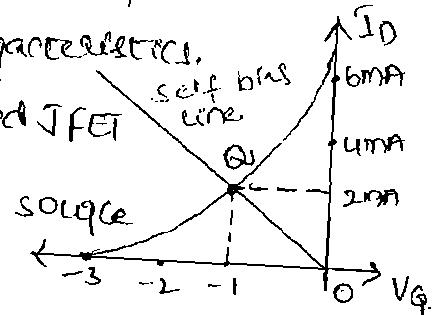
Applying KVL at d/p we get

$$V_S + V_{DS} + I_D R_D = V_{DD}$$

$$\Rightarrow V_{DS} = V_{DD} - V_S - I_D R_D = V_{DD} - I_{DSS} \left(R_S + R_D \right)$$

-for self-bias we know that $V_S = I_D R_S$; $V_{GS} = -V_S = -I_D R_S$

These equations can be used with a transfer characteristic. The next fig shows a typical transfer characteristic (Transconductance Curve) for a self biased JFET. The max drain current is 6mA, and gate to source cutoff voltage is -3v.



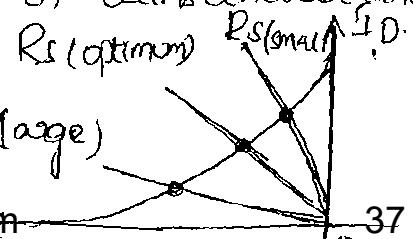
Now using equation $V_{GS} = -I_D R_S$ and assuming R_S of any suitable value we can draw the self bias line. Let assume, $R_S = 500\Omega$. With this R_S we can plot two convenient points corresponding to $I_D = 0$ and $I_D = I_{DSS}$, at first point, $I_D = 0$.

$$\therefore V_{GS} = -0(500\Omega) = 0V \text{ and at second point, } I_D = 6mA$$

$$\therefore V_{GS} = -(6mA)(500\Omega) = -3V.$$

This gives co-ordinates of two points as (0,0) and (6mA, -3V) ges. By plotting these two points, we can draw the straight line through the points as shown in above fig. This line will intersect the transconductance curve and it is known as self bias line. The intersection point gives operating point of the self biased JFET for this circuit. At operating point drain current is slightly greater than 6mA and gate voltage is slightly less than -1V.

The Q-point for self bias JFET depends on value of R_S . When R_S is large, the Q-point is far down on transconductance curve, when drain current is small. When R_S is small, the Q-point is far up on transconductance curve when drain current is large.



Effect of temperature drift

In JFET, the drain current varies with

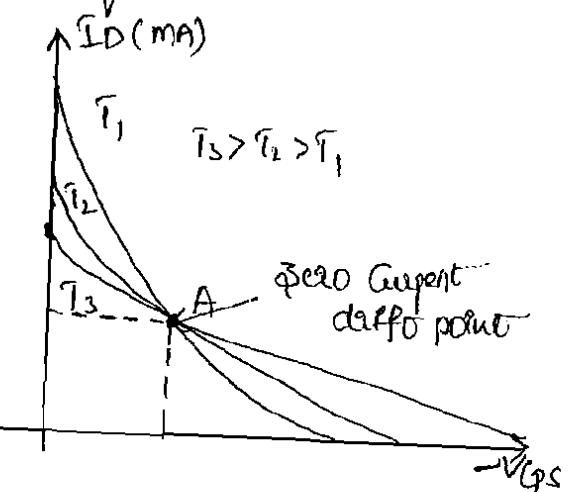
changes in temperature due to two factors. one factor increases drain current and other factor decreases drain current with increase in temperature. Therefore it is possible to design biasing circuit which compensates these two factors so that there is no change of drain current with temperature. such a biasing is called biasing for zero Current drift.

1) First factor is the decrease of majority-carrier mobility with increase in temperature. As temperature increases, the lattice ions vibrate more vigorously, and hence carriers cannot move freely in crystalline structure. The reduction in μ is 0.7% for 1°C increase in temperature.

2) The second factor is the decrease of width of depletion region (i.e. of increase in channel width) with increase in temperature. This allows I_D to increase and increase in I_D is equivalent to a change of 22mV/°C in V_{GDS} .

Derivation of condition for zero drift:

Since a change in gate voltage ΔV_{GDS} causes a change in drain current of $\Delta I_D = g_m \Delta V_{GDS}$, the condition for zero drift is



$$0.007/I_D = g_m 0.0022 \quad (\text{for } 1^\circ\text{C rise of temperature})$$

$$\Rightarrow \therefore \frac{|I_D|}{g_m} = 0.314V; \quad \text{as we know}$$

$$I_D = I_{DSS} \left[1 - \frac{V_{GDS}}{V_P} \right]^2 \quad \text{and} \quad g_m = -\frac{2I_{DSS}}{V_P} \left[1 - \frac{V_{GDS}}{V_P} \right]$$

$$I_D = I_{DSS} \left[1 - \frac{V_P + V_{GS}}{V_P} \right] = I_{DSS} \left[1 - \frac{V_P + 0.63}{V_P} \right] = I_{DSS} \left[1 - \frac{1.63}{V_P} \right]$$

$$\Rightarrow |V_P| - |V_{GS}| = -0.628 \text{ V} = -0.63 \text{ V}$$

from above if we know value of V_P , we can obtain the value of V_{GS} for zero drain current when V_{GS} is adjusted for zero drain current, I_D and g_m are.

$$I_D = I_{DSS} \left[1 - \frac{V_P + 0.63}{V_P} \right]^2 = I_{DSS} \left[\frac{0.63}{V_P} \right]^2$$

$$g_m = g_{m0} \left[1 - \frac{V_P + 0.63}{V_P} \right] = g_{m0} \left[\frac{0.63}{|V_P|} \right]$$

Biasing against device variation:

FET manufacturer usually specify information on the maximum and minimum values of I_{DSS} and $I_{DSS(\min)}$

V_P at room temperature

they also specify data to correct these quantities for temperature variations the top and bottom curves are for extreme values of temperature and device variations.

Let assume I_D

is not allowed to drift outside

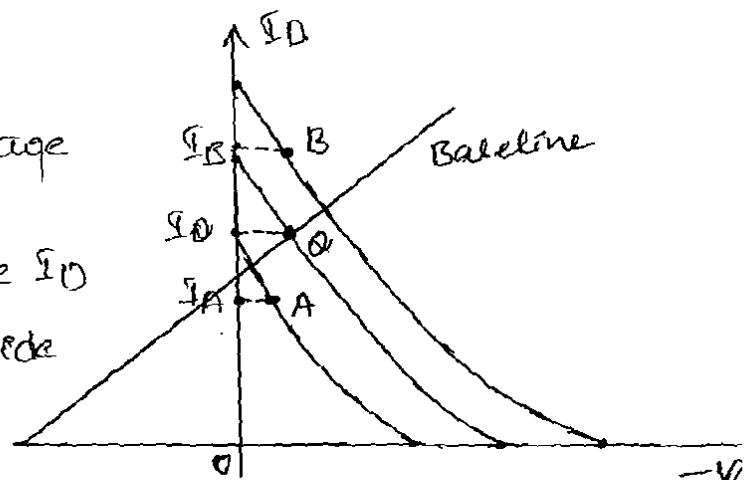
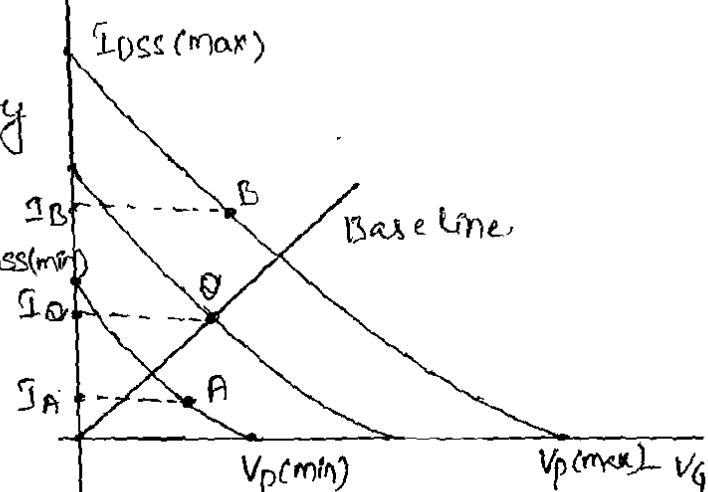
$I_D = I_A$ and $I_D = I_B$. then the

base line $V_{GS} = -I_D R_S$ must

intersect the transfer characteristics b/w points 'A' and 'B'.

I_Q always have values b/w I_A and I_B such that

$I_A < I_Q < I_B$.



Practical bias is often slightly different than in ideal.

A line drawn to pass between points ii and iii does not pass through the origin. This practical bias line is represented mathematically as $V_{GDS} = V_{GG} - \frac{I_D}{R_D}$.

Such a bias relationship may be obtained by adding a fixed bias to the gate in addition to the self bias, this requires two power supplies. The self bias circuit with additional voltage divider requires only one power supply.

for voltage divider bias: $V_{GG} = \frac{R_2}{R_1 + R_2} \times V_{DD}$; $R_g = R_1 || R_2 = \frac{R_1 R_2}{R_1 + R_2}$

We assumed that gate current is negligible. It is also possible for V_{GG} to fall in the -ve biased region so that the line in (b) intersects the horizontal axis to the right of origin. Under these circumstances two separate supply voltages must be used.

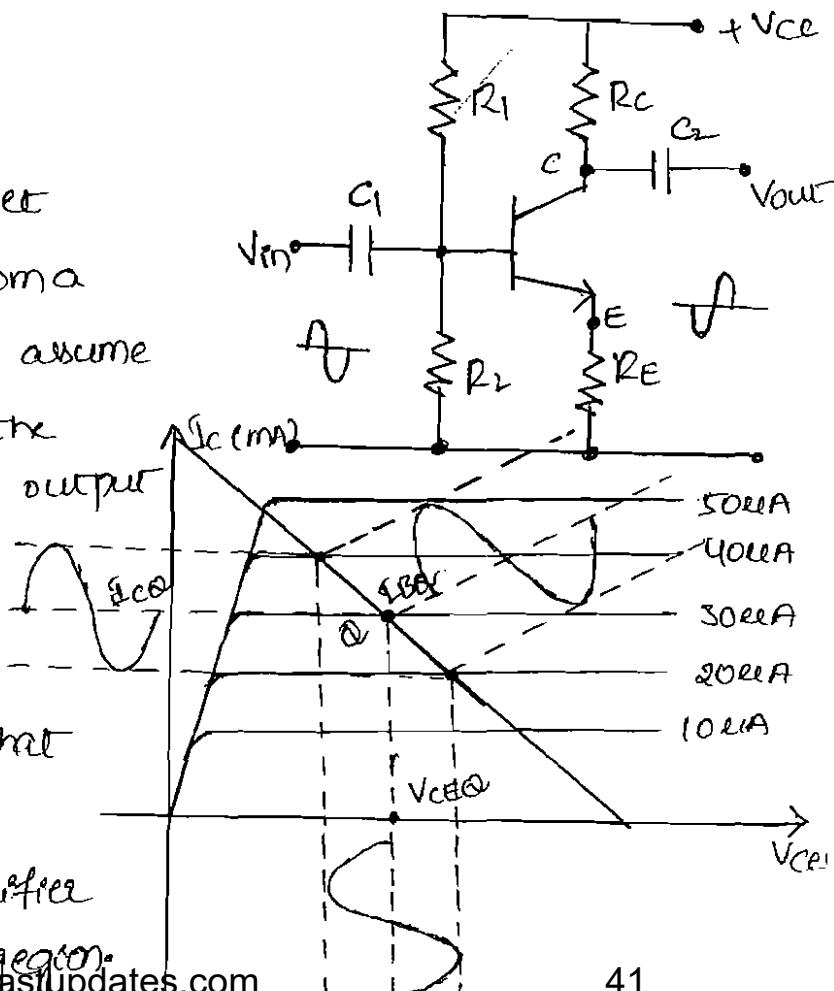
We know that V-I characteristics of an active device such as BJT are non linear, with complicated analysis procedure. To simplify analysis of BJT P-Es operation is restricted to linear V-I characteristics around Q-point i.e. in active region. This is possible only with small R.P. signals. The term small signal amplifier refers to the use of signal that takes up a relatively a small percentage of an amplifier's operational range. With small signals, the transistor can be replaced with small signal linear model. This model is also called small signal equivalent circuit.

We know that reactance of a capacitor is $X_C = \frac{1}{\omega C}$. For low frequencies the values of junction capacitors are very high, as they appear in parallel with junctions, their effect is ignored at low frequencies and analysis is further simplified.

CE, CB and CC Amplifiers:

The amplifier is used to get a larger signal output from a small signal input. We will assume a sinusoidal signal at the R.P. of amplifier. At the output signal must remain sinusoidal in waveform with frequency same as that of input.

To make the transistor work as an amplifier it is to be biased in active region.



(or) Current mirror amplifier or using self bias
(or) voltage divided bias

In the absence of i/p signal, only d.c. voltage are present in the circuit. This is known as zero-signal (or) no-signal condition (or) quiescent condition for the amplifier. The d.c. collector-emitter voltage, V_{CE} , the d.c. collector current I_C , and d.c. base current I_B is the quiescent operating point for the amplifier. On this d.c. quiescent operating point, we superimpose a.c. signal by application of a.c. sinusoidal voltage at the input due to this base current varies sinusoidally.

Since the transistor is biased to operate in the active region, the output is linearly proportional to the i/p. I_C is β times larger than i/p base current I_B in CE configuration. Hence collector current will also varies sinusoidally about its quiescent value, I_{CQ} . The output voltage will also vary sinusoidally.

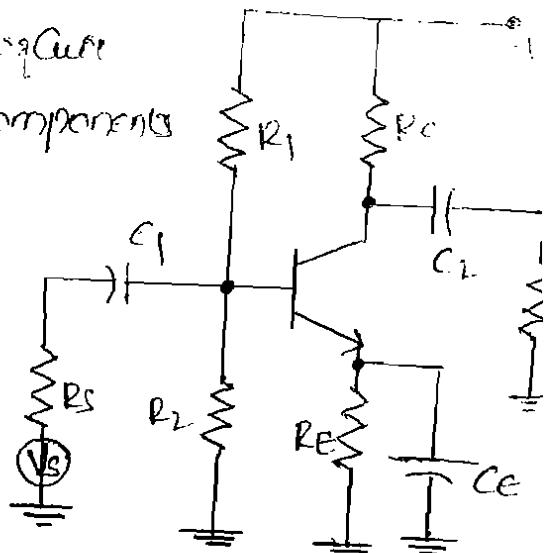
The collector current varies above and below its Q-point value in-phase with the base current, and the collector to emitter voltage varies above and below its Q-point value anti-phase (180°) with base voltage.

When one cycle of i/p is completed, one cycle of output will also be completed. This means the frequency of output sinusoidal is same as the frequency of i/p sinusoid. Thus in amplification process, frequency of o/p signal does not change. Only the magnitude of o/p is larger than that of i/p signal.

The CE Amplifier consists of different circuit components, the functions of these components are

1) Biasing Circuit:

the Resistances R_1 , R_2 and R_E forms the voltage divider biasing circuit for the CE Amplifier. It sets proper operating point for the CE Amplifier.



2) Input Capacitor C_1 :

This capacitor couples the signal to the base of the transistor. It blocks any d.c. component present in the signal and passes only a.c. signal for amplification. Because of these biasing conditions age maintained constant.

3) Emitter Bypass Capacitor C_E :

An Emitter bypass capacitor C_E is connected in parallel with emitter resistance, R_E to provide a low impedance path to the amplified a.c. signal. If it is not inserted, the amplified a.c. signal passing through R_E will cause a voltage drop across it. This will reduce d.c. voltage, reducing gain of amplifier.

4) Output Coupling capacitor C_2 :

C_2 couples the output of the amplifier to the load (or) to the next stage of amplifier. It blocks d.c. and passes only a.c. part of amplified signal.

The coupling capacitors acts as open circuit for d.c. and short circuit for a.c. components.

Common Emitter Amplifier

The d.c. biasing is provided by R_1 , R_2 and R_E .

The load resistance is capacitor coupled to the emitter terminal of the transistor.

When a signal is applied

Via to the base of the transistor, V_B is increased and decreased

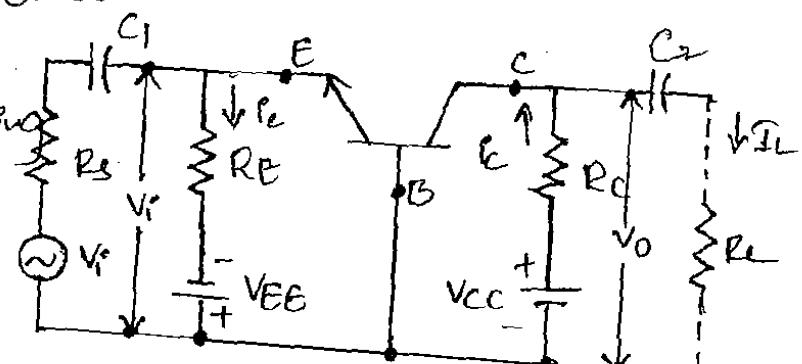
as the signal goes +ve & -ve

We can note that $V_E = V_B - V_{BE}$, considering V_{BE} fairly constant, we can say that variations in the V_B appears at emitter, and emitter voltage V_E will vary same as base voltage V_B . It can be noted that d.c. voltage from a common collector circuit is same as d.c. voltage. Hence Common Collector Circuit is also known as emitter follower.

Common Base Amplifier Circuit

Signal source is connected to the emitter via coupling capacitor C_1 .

Load resistor is connected to collector via coupling capacitor C_2 .



The positive going pulse of d.c. source increases emitter voltage. As base voltage is const, the forward bias of JF junction reduced. This reduces I_B , hence I_C hence drop across R_C . Since $V_b = V_{CC} - I_C R_C$, the reduction in I_C results increase in V_b . So positive going pulse produces positive output. Hence there is a